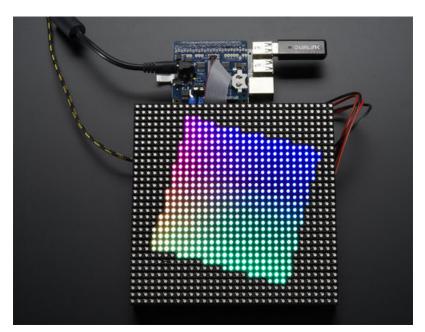


Adafruit RGB Matrix + Real Time Clock HAT for Raspberry Pi

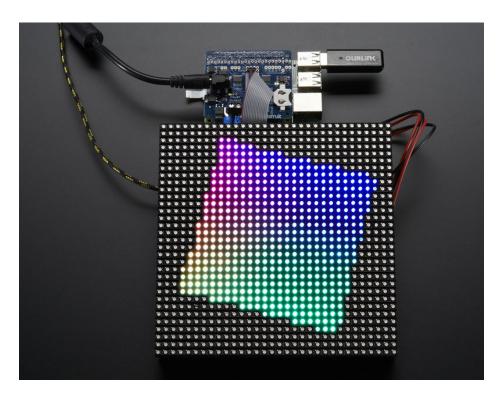
Created by lady ada



Last updated on 2020-02-07 07:34:47 PM UTC

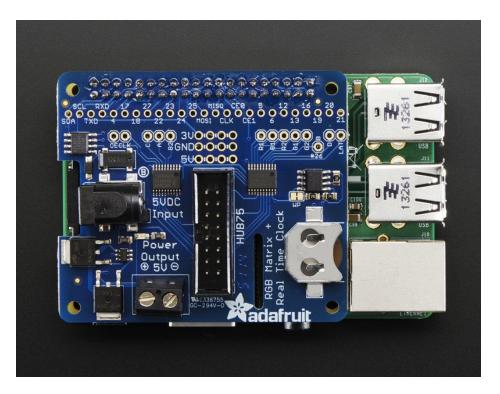
Overview





You can now create a dazzling display with your Raspberry Pi with the Adafruit RGB Matrix HAT or Bonnet. These boards plug into your Pi and makes it super easy to control RGB matrices such as those we stock in the shop and create a colorful scrolling display or mini LED wall with ease.

The RGB Matrix HAT works on any Raspberry Pi with a 40-pin GPIO header — Zero, Zero W/WH, Model A+, B+, Pi 2, 3 and 4. It *does not work* with older 26-pin boards like the original Model A or B. Note with the Pi Zero you may need to solder a header on the Pi board; it's normally unpopulated on that model (except the "Zero WH").



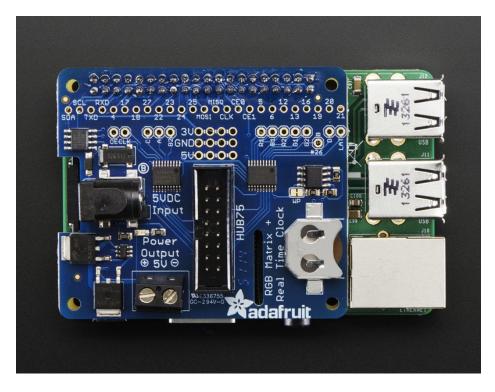
This HAT is our finest to date, full of some really great circuitry. Let me break it down for you:

- Simple design plug in power, plug in IDC cable, run our Python code!
- **Power protection circuitry** you can plug a 5V 4A wall adapter into the HAT and it will automatically protect against negative, over or under-voltages! Yay for no accidental destruction of your setup.
- Onboard level shifters to convert the RasPi's 3.3V to 5.0V logic for clean and glitch free matrix driving
- DS1307 Real Time Clock can keep track of time for the Pi even when it is rebooted or powered down, to make for really nice time displays



Works with any of our 16x32, 32x32 or 32x64 RGB LED Matrices with HUB75 connections(https://adafru.it/emd). The latest "Rev C" HAT also supports 64x64 matrices by soldering a small jumper on the PCB. You can even chain multiple matrices together for a longer display - we've only tested up to 32x128 but it works just fine. The bigger the display the harder it is on the Pi, so keep that in mind if you're using a lower-powered Pi Zero.

Please note: this HAT is only for use with HUB75 type RGB Matrices. Not for use with NeoPixel, DotStar, or other 'addressable' LEDs.



Each order comes with a HAT PCB with all surface mount parts assembled, a 2x20 female socket connector, a 2 pin terminal block, and a 2x8 IDC socket connector. A CR1220 coin cell is not included to make air shipping easier, please order one seperately (https://adafru.it/em8) if you do not have one and would like to use the real time clock.

RGB Matrix is not included, please check out our fine selection (https://adafru.it/emd)!

A 5V power supply is also required, not included, for power the matrix itself, the Pi cannot do it, to calculate the power, multiply the width of all the chained matrices * 0.12 Amps : A 32 pixel wide matrix can end up drawing 32*0.12 = 3.85A so pick up a 5V 4A power supply (https://adafru.it/e50).

Raspberry Pi not included (but we have 'em in the shop so pick one up) (https://adafru.it/eme)

Some light soldering is required to attach the headers to your Pi. A soldering iron and solder are required, but it's a simple soldering job and most beginners can do it in about 15 minutes.



Pinouts

This HAT uses **a lot** of pins to drive the RGB Matrix. You'll still have a couple left over but just be aware a majority are in use by the matrix.

Unused GPIO pins include: RX, TX, 25, MOSI, MISO, SCLK, CE0, CE1, 19.

Pin 24 is free if you are not using a 1/32 scan (i.e. 64x64) matrix.

Pin 18 is free if using the "convenience" (vs "quality") setting during installation.

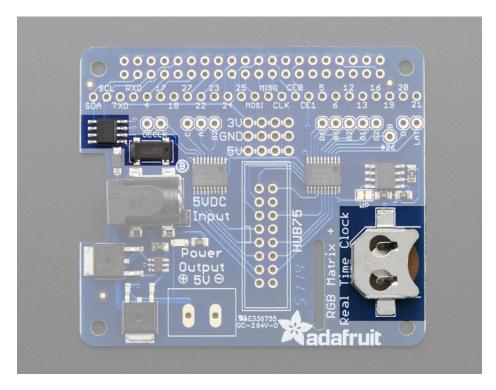
The **1-Wire** interface as enabled by raspi-config will interfere with the operation of the matrix! By default it uses pin 4. If you are connecting any 1-Wire devices, specify a **different pin** (any of the above) in /boot/config.txt, for example:

dtoverlay=w1-gpio gpiopin=19

I2C / RTC pins

The DS1307 Real Time Clock soldered onboard is connected to the I2C pins **SDA** and **SCL** - these can still be used for other I2C sensors and devices as long as they are not on address 0x68

To use the Real Time Clock, a CR1220 3V lithium battery is required.



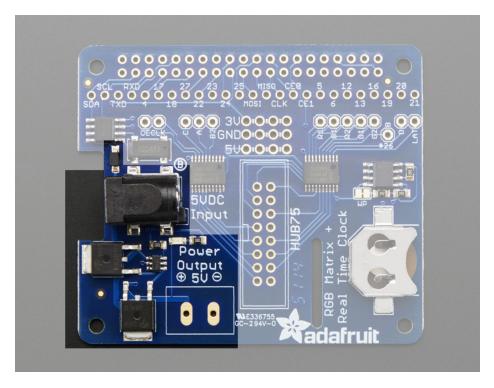
5V protection circuitry and backpower diode

LED matrix panels require 5V power and **a lot of it!** 5V 2A at a minimum and you can easily need a 5V 4A or 5V 10A supply for big stretches of panels!

Each matrix has 64 pixels (16x32 or 32x32 panels) or 128 pixels (for the 32x64 panels) lit at one time. Each pixel can

draw up to 0.06 Amps each if on full white. The total max per panel is thus 64 * 0.06 = 3.95 Amps or 128 * 0.06 = 7.68 Amps

That's if all the LEDs are on at once, which is not likely - but still, its good to have at least half for the power supply in case you get bright!



5V power from a wall plug goes into the DC jack on the HAT which then goes through a fancy protection circuit that makes sure the voltage is not higher than 5.8V - this means that if you accidentally grab a 9V or 12V plug or a reverse polarity plug you will not damage the HAT, Pi and panels. (Please note, this does not protect against extreme damage, if you plug in a 120VAC output into the DC jack or continuously try to plug in the wrong voltage you could still cause damage so please do be careful!)

We recommend powering your driving Raspberry Pi from the Pi's microUSB port but we do have a 1A diode on board that will automatically power the Pi if/when the voltage drops. So if you want, just plug in the 5V wall adapter into the HAT and it will automagically power up the Pi too!

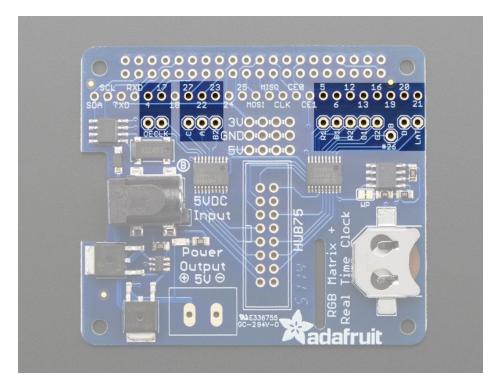
The green LED next to the DC jack will indicate that the 5V power is good, make sure it is lit when trying to use the HAT!

Matrix Drive pins

The matrix does not work like 'smart' pixels you may have used, like NeoPixels or DotStars or LPD8806 or WS2801 or what have you. The matrix panels are very 'dumb' and have no memory or self-drawing capability.

Data must be constantly streamed to the matrix for an image to display! So all of these pins are always used when drawing to the display

All these pins go thru a 74AHCT145 level shifter to convert the 3.3V logic from the Pi to the 5V logic required by the panels



Matrix Color Pins

- Pi GPIO **#5** Matrix R1 (Red row 1) pin This pin controls the red LEDs on the top half of the display
- Pi GPIO #13 Matrix G1 (Green row 1) pin This pin controls the green LEDs on the top half of the display
- Pi GPIO #6 Matrix B1 (Blue row 1) pin This pin controls the blue LEDs on the top half of the display
- Pi GPIO #12 Matrix R2 (Red row 2) pin This pin controls the red LEDs on the bottom half of the display
- Pi GPIO #16 Matrix G2 (Green row2) pin This pin controls the green LEDs on the bottom half of the display
- Pi GPIO **#23 Matrix B2** (Blue row 2) pin This pin controls the blue LEDs on the bottom half of the display

Matrix Control pins

- Pi GPIO #4 Matrix OE (output enable) pin This pin controls whether the LEDs are lit at all
- Pi GPIO #17 Matrix CLK (clock) pin This pin is the high speed clock pin for clocking RGB data to the matrix
- Pi GPIO **#21 Matrix LAT** (latch) pin This pin is the data latching pin for clocking RGB data to the matrix

RGB Matrix Address pins

- Pi GPIO **#22** Matrix A (address A) pin This pin is part of the 1->16 or 1->8 multiplexing circuitry.
- Pi GPIO **#26 Matrix B** (address B) pin This pin is part of the 1->16 or 1->8 multiplexing circuitry.
- Pi GPIO #27 Matrix C (address C) pin

This pin is part of the 1->16 or 1->8 multiplexing circuitry.

- Pi GPIO #20 Matrix D (address D) pin This pin is part of the 1->32, 1->16 multiplexing circuitry. Used for 32-pixel and 64-pixel tall displays only
- Pi GPIO #24 Matrix E (address E) pin
 This pin is part of the 1->32 multiplexing circuitry. Used for 64-pixel tall displays only. Present on newer "Rev C" HATs only. Requires minor soldering, explained on next page.

Assembly



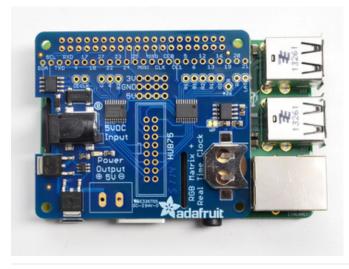


Solder on Headers and Terminal Block

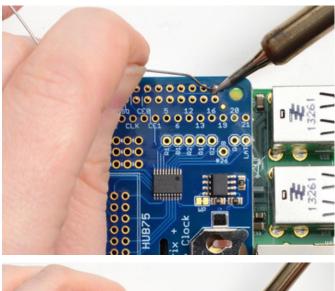
Before we can a-blinkin' there's a little soldering to be done. This step will attach the 2x20 socket header so that we can plug this HAT into a Raspberry Pi, the 2x8 header so we can plug the RGB matrix into the HAT, and a terminal block so you can power the matrix through the HAT.



Start by plugging the 2x20 header into a Raspberry Pi, this will keep the header stable while you solder. Make sure the Pi is powered off!



Place the HAT on top so that the short pins of the 2x20 header line up with the pads on the HAT



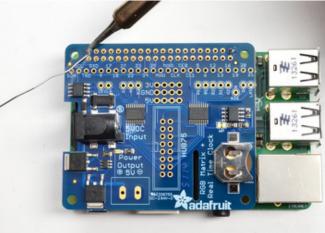
And Solder!

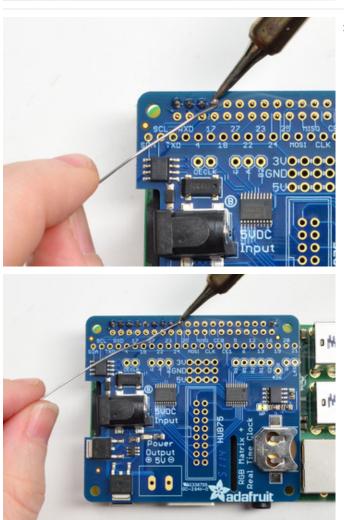
Heat up your iron and solder in one header connection on the right.

Once it is soldered, put down the solder and reheat the solder point with your iron while straightening the HAT so it isn't leaning down

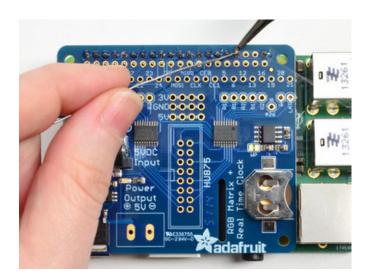
(For tips on soldering, be sure to check out our Guide to *Excellent Soldering* (https://adafru.it/aTk)).

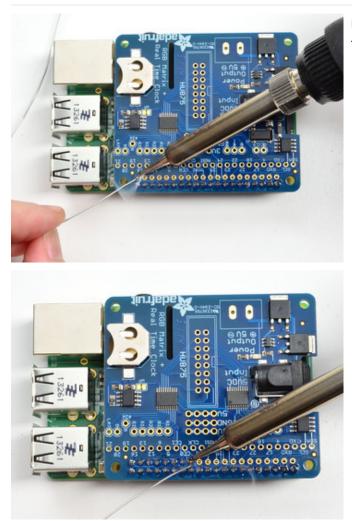




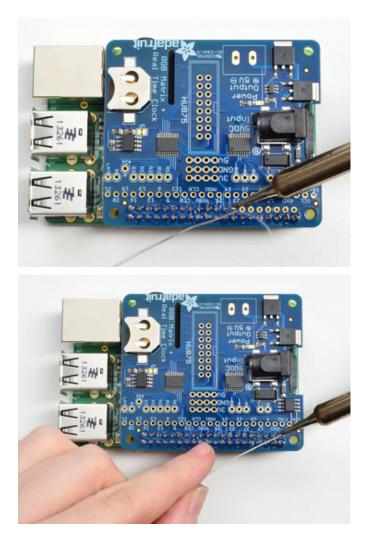


Solder each of the connections for the top row



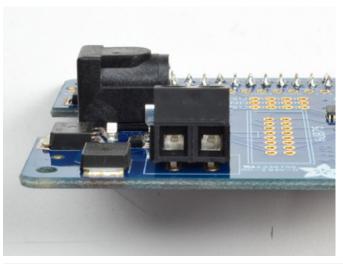


Flip the board around and solder all the connections for the other half of the 2x20 header





Check over your work so far, make sure each solder point is shiny, and isn't bridged or dull or cracked



Place the 2 pin terminal block first, make sure the two 'mouths' are facing outwards

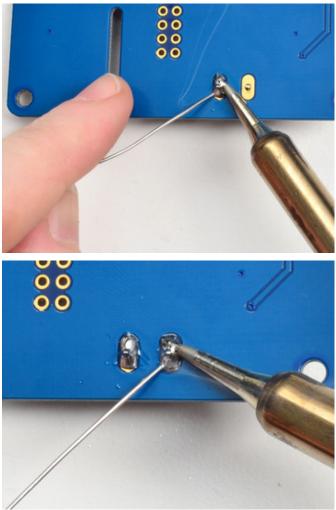


Use some tape to stick the terminal down in place



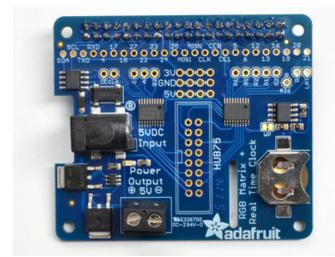
Flip the board over, the tape should keep the terminal block in place







Check your work, the connections should be solid and shiny



Next up we will attach the 2x8 IDC header. Unlike the 2x20 header, this connector has a direction!

Notice in the middle there's an outline for the connector in the middle. On the right it says **HUB75** and on the left of the connector there is a little 'cutout' shape. This cutout shape must match up with the cut out on the connector.

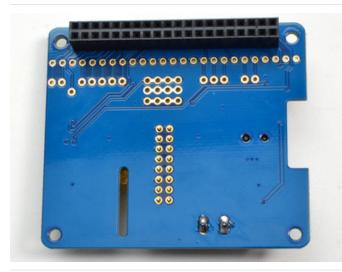
If you solder it in backwards, its not a huge deal, you can use diagonal cutters to cut out a notch on the opposite side, but if you get it right then you will never have to worry about plugging in your matrix data cable the wrong way



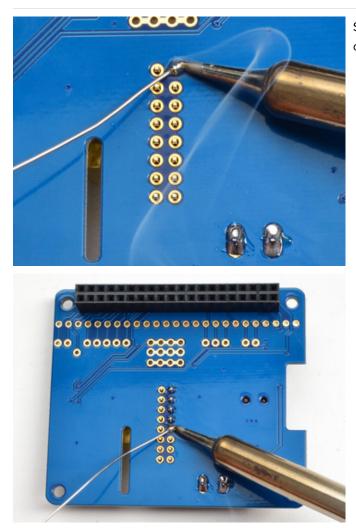
Place the connector in the slot so that the notched side is on the **left**



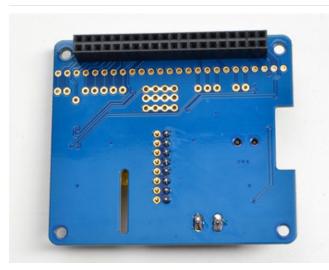
Use some tape to hold the IDC connector in place



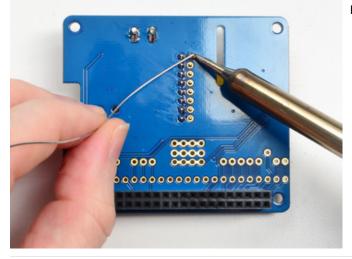
Flip the board over, the tape should keep the connector from falling out



Solder in all the pins like you did with the 2x20 connector

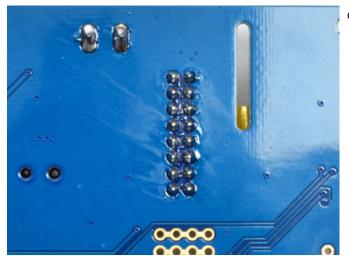


Check your work! Make sure all the solder points are clean and not shorted or cracked or dull



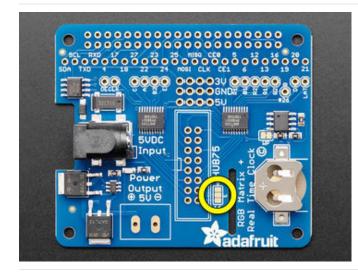
Flip the board around & solder up the other half!

Check your work one last time...now continue to testing!



64x64 Matrices: Solder "E" Jumper

64x64 matrices are supported on the latest "Rev C" HATs only.

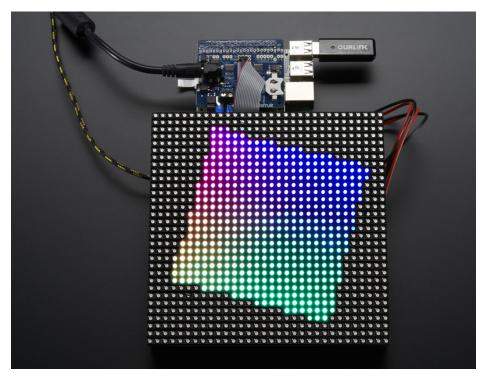


Look for the Address E pads located between the HUB75 connector and Pi camera cutout.

Melt a blob of solder between the center "E" pad the the "8" pad just above it (for 64x64 matrices in the Adafruit shop)...*or* the "16" pad below (rare, for some third-party 64x64 matrices...check datasheet).



Driving Matrices



OK we're onto the fun part now! Be sure you have completed the Assembly step before continuing, the soldering is **not optional**

Step 1. Plug HAT/Bonnet into Raspberry Pi

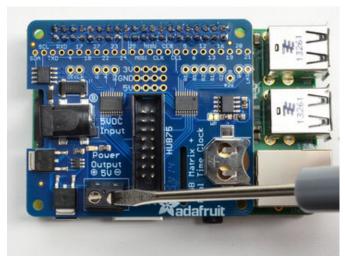


Step 2. Connect Matrix Power cable to terminal block

Your RGB matrix came with a red & black power cable. One end has a 4-pin MOLEX connector that goes into the matrix. The other end probably has a spade connector. If you didn't get a spade connector, you may have to cut off the connector and tin the wires to plug them into the terminal block

Shut down your Pi and remove power. Plug the HAT or Bonnet on so all the 2x20 pins go into the GPIO header.

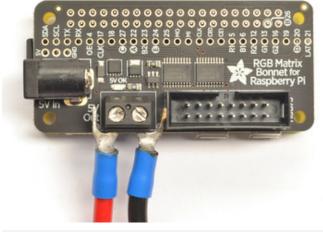
Either way, unscrew the terminal blocks to loosen them



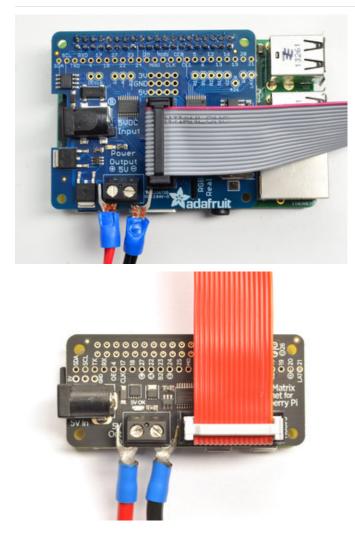




Plug the red wire into the + side, and the black wire into the - side.



Step 3. Connect RGB Matrix Data cable to IDC

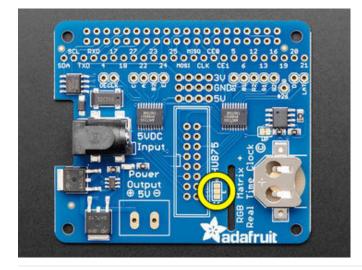


The RGB matrix also came with a 2x8 data cable. Connect one end to the matrix's INPUT side and the other end to the IDC socket on the HAT/bonnet.

It wont damage the matrix if you accidentally get the cable connected to the output end of the matrix but it wont work so you might as well get it right first time!



If you're using a **64x64** RGB matrix and either a Bonnet or a Rev C HAT, use your soldering iron to melt a blob of solder on the bottom solder jumper so the middle pad is 'shorted' to **8**. (*This is compatible with 64x64 matrices in the Adafruit store. For 64x64 matrices from other sources, you might need to use 16 instead, check the datasheet.*)

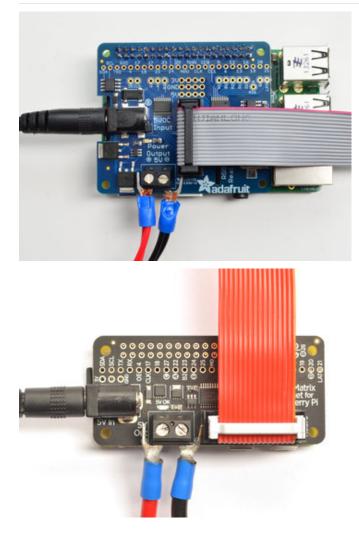


Step 4. Power up your Pi via MicroUSB (optional but suggested)

Connect your Raspberry Pi to power via the microUSB cable, just like you normally would to power it up.

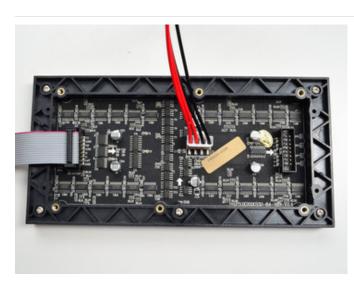
You can power the Pi via the 5V wall plug that is also used for the Matrix but its best to have it powered seperately

Step 5. Plug in the 5V DC power for the Matrix



OK now you can plug in your 5V 2A or 4A or larger wall adapter into the HAT/bonnet. This will turn the green LED on but nothing will display on your matrix yet because no software is running!

Check that the Matrix plugs are installed and in the right location



IDC goes into the INPUT side (look for any arrows, arrows point from INPUT side to OUTPUT)

Power plug installed, red wires go to VCC, black wires to GND

Step 6. Log into your Pi to install and run software

OK now you are ready to run the Pi software. You will need to get into a command line via the HDMI monitor, ssh or console cable. You will also need to make sure your Pi is on the Internet via a WiFi or Ethernet connection.

We have a script that downloads the code and any prerequisite software. It works with the current **Raspbian "Buster"** (or earlier "Stretch") operating system (either the Lite or Desktop version):

```
curl https://raw.githubusercontent.com/adafruit/Raspberry-Pi-Installer-Scripts/master/rgb-matrix.sh
>rgb-matrix.sh
sudo bash rgb-matrix.sh
```

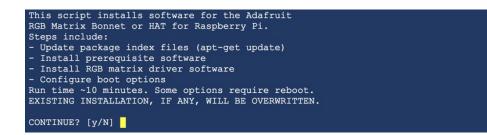
The LED-matrix library is (c) Henner Zeller <u>h.zeller@acm.org</u> with GNU General Public License Version 2.0 http://www.gnu.org/licenses/gpl-2.0.txt (https://adafru.it/ewN)

Earlier versions of this guide used our own fork of this library. That's **deprecated** now, but still available (https://adafru.it/ewy)if you have existing code built atop it. Otherwise, use this installer script and latest code.

-	r <mark>aspber</mark> Install		~ \$ curl ripts/ma					ercontent	t.com/ada	fruit/R	aspberry
*	Total	8	Received	% Xf	erd		e Speed Upload	Time Total	Time Spent		Current Speed
100		100	6025	0	0	15257	_0		::		
pi@1	caspber	rypi:	sudo	bash	rgb	-matrix	.sh				

When first run, the script will explain its plans and give you the option to cancel.

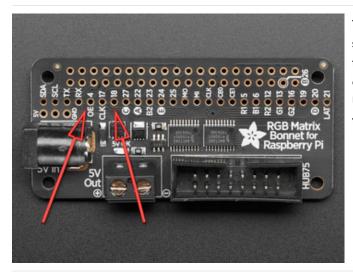
Of particular note here: any existing installation will be replaced. If there is a directory called "rpi-rgb-led-matrix" in the current working directory, its contents will be overwritten. Additionally, a Python module is installed and will replace anything currently there. If this is a problem, cancel and make a backup. Otherwise, sometimes reinstalling is exactly what you want.



Next the script will ask you what kind of adapter you're using between the Pi and RGB matrix: either an Adafruit RGB Matrix Bonnet, or RGB Matrix HAT with RTC. If you select the latter, you'll also be asked if you want to install additional drivers for the realtime clock.



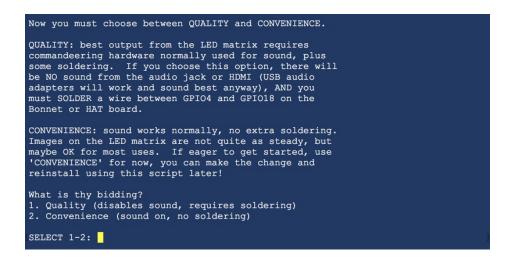
Then you're asked whether you need the *absolute best image possible* from the LED matrix, or can accept slightly reduced quality for the sake of simplicity.



The "quality" option comes at a cost. First, you need to solder a jumper wire between GPIO4 and GPIO18 on the Bonnet or Hat board. Also, the normal sound output of the Raspberry Pi must be disabled. You can still use a USB sound adapter if needed, but audio over HDMI or from the 1/8" jack will not be present.

The "convenience" setting requires no changes and sound still works. For many casual projects this might look good enough. There's an occasional bit of flicker from the matrix, that's all.

If you're not sure, or if you just want to get started experimenting with your new gadget, select "convenience" for now. You can make the change and reinstall the software later if needed.



The script will confirm your selections and offer one more chance to cancel without changes.

There's a lot of software to update, download and install, so it may take up to **15 minutes** or so to complete. Afterward, you'll be asked whether you want to **reboot** the system. If you've selected to install RTC support (for the Matrix HAT + RTC) or have made a change in the "quality" vs "convenience" setting, a reboot is required.

All other settings (LED matrix size, number of "chained" matrices and so forth) are specified at run-time.



Testing the Examples

The installer creates a directory called **rpi-rgb-led-matrix**, and inside this is a subdirectory **examples-api-use** with a few programs we can use to experiment with the matrix and confirm everything's working.

All of the examples — and any code using the companion libraries — accept a common set of command-line switches for specifying the LED matrix size and other options. Among the more vital options are:

--led-rows= (rows)

Specifies the number of rows (or height or the number of pixels vertically) of your LED matrix (or matrices, if you have several chained...they all need to be the same size though). Default value if unspecified is **32**. Maximum value with the Adafruit **RGB Matrix HAT + RTC** is **32**. Maximum with the **RGB Matrix Bonnet** is **64**.

--led-cols= (columns)

Specifies the number of columns (or width or the number of pixels horizontally) of your LED matrix/matrices. Default value if unspecified is **32**.

--led-chain= (chained)

Specifies the number of matrices in the chain...the output of one connects to the input of the next. Default value if unspecified is **1**.

Here's how to run one of the examples — a rotating colored square. Because this code is performing low-level hardware operations, it must be run using the sudo command:

sudo ./demo -D0 --led-rows=32 --led-cols=16

That's for a single 32x16 pixel RGB matrix. If you have a different size, change the --led-rows and/or --led-cols values. Add a --led-chain value if multiple matrices are chained.

There are 12 different examples in the demo program (0 through 11), chosen with -D. For a full list of the program's options, just type demo.

Depending on your matrix type and Raspberry Pi model, some additional options may need fine-tuning:

--led-slowdown-gpio= (0...n) Sometimes needed to throttle back the speed when using a fast Pi. Default is 1.

For Raspberry Pi 3 use a slowdown of 1 to start (use higher values if image still flickers). For Raspberry Pi 4, use a slowdown of 4. Older Pi models might work with 0, try it.

--led-rgb-sequence= (RGB order) Some LED matrices may have their red, green and blue LEDs wired up in a different order...for example, if you need to swap the green and blue channels, use --led-rgb-sequence=RBG. Default is RGB.

--led-pwm-bits= (1...11) For long matrix chains you'll probably need to use fewer PWM bits, sacrificing some color fidelity to improve refresh speed. Default is 11.

There are still many **additional options** but they're **increasingly esoteric** and might only be needed with RGB matrices from other sources. For a complete explanation of these options (and a more in-depth explanation of the options above) see the **documentation accompanying hzeller's code repository (https://adafru.it/kdg).**

The demos kinda run, but I'm seeing weird rectangles and glitches.

If your Pi is overclocked, or if you're using a Raspberry Pi 2 or Pi 4, you may need to dial back the matrix control speed slightly. This can be done with the --led-slowdown-gpio=2 setting. Pi 4 may require larger values, depending on the matrix...experiment! Conversely, early Raspberry Pis (Model A, B and similar) might get an improved image by speeding up the matrix code with a value of 0 here.

There are a few additional examples in that directory showing how to write C++ programs to draw to the matrix. Look through the source code and Makefile to see how this is done and how to link with the **rgbmatrix** library. And there's more documentation in the hzeller repository (https://adafru.it/BhV), including initializing the matrix size and chain length in your code so it's not necessary to specify this on the command line every time.

Using the Python Library

Some Python examples are included in the **rpi-rgb-led-matrix/bindings/python/samples** directory. The matrix installer script has already loaded the prerequisite Python Imaging Library and installed the **rgbmatrix** module for both Python 2.7 and Python 3.

Again, more documentation is available in the library author's repository (https://adafru.it/BhW), and some of the examples show how to specify the matrix size and chain length in code rather than command-line selections every time.

While the **rgbmatrix** module provides its own drawing operations, it can also work with the Python Imaging Library as an "offscreen canvas" that's then issued to the matrix with the SetImage() or SwapOnVSync() function — see the examples with "image-" in their name.

Core PIL image functions are explained here: The Image Module (https://adafru.it/dvE)

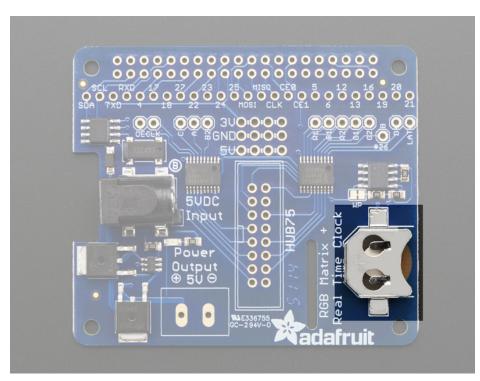
Graphics functions (lines, etc.) are here: The ImageDraw Module (https://adafru.it/dfH)

Reminder: the older Adafruit fork of the RGB matrix library (https://adafru.it/ewy) is still available if you need it for existing code, but consider this deprecated. For new projects we recommend the more up-to-date hzeller code installed by the **rgb-matrix.sh** script!



Using the RTC

We had a little space and thought a real time clock would be a nice pairing for this HAT so we tossed on a DS1307 real time clock (RTC). This clock uses a 32.768KHz crystal and backup battery to let the HAT & Pi keep track of time even when power is lost and there's no network access. This makes it great for time displays!



A 12mm 3V Lithium Coin Cell (CR1220) is REQUIRED to use the RTC! It will not work without one! (https://adafru.it/em8)

The **rgb-matrix.sh** script already installed the necessary software to use the realtime clock...but you'll need to set the initial time once. This is explained in the **"Sync time from Pi to RTC"** section of this DS1307 tutorial (https://adafru.it/IF1) (just that one section...you can ignore the rest).





The matrix looks like it's trying to work, but the image is all flickery.

Try using the --led-slowdown-gpio=X command-line setting, where "X" ranges from 0 (for the very earliest Raspberry Pi models) up to 4 (for the Raspberry Pi 4). Experiment to find the **lowest value** that provides a **stable image** on your system.

I'm using a Raspberry Pi 2 and things are all not working right!

Run **sudo raspi-config** and in the "Overclock" options set the core frequency to 350 MHz or less. Reboot and see if the image is stable. There seems to be an issue when toggling GPIO too quickly.

Also see the prior note about dialing back the GPIO speed.

The matrix flashes on and off when in use

If you're interfacing to any **1-wire** devices, and if you've enabled 1-wire via raspi-config, you'll need to use something other than the default pin 4. Pins 19 or 25 make good choices. Look for the line in **/boot/config.txt** where 1-wire is enabled and tell it which pin to use:

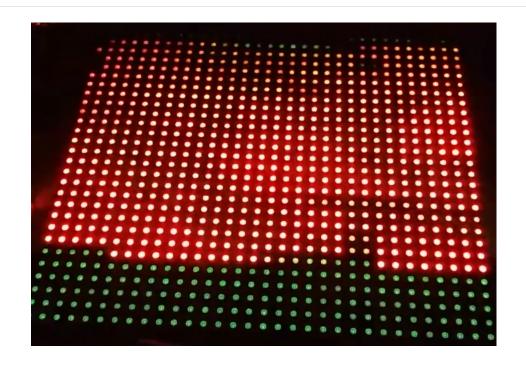
dtoverlay=w1-gpio gpiopin=19

Tried all these, it still flickers.

Large LED matrices and newer model Raspberry Pis need more power than the early days. If you're trying to run everything from a 5V 2 Amp power supply, you probably need to step up to 4A or better. You can also try powering the Raspberry Pi from a USB power supply and the matrix (via the HAT or Bonnet) with a DC supply.

My display has dim red LEDs or has odd output

Check that you have plugged in a good 5V 2A+ (4A+ is best) power supply into the Bonnet/HAT. **The Raspberry Pi's 5V power supply cannot power a matrix, you need a separate high current supply as well!**





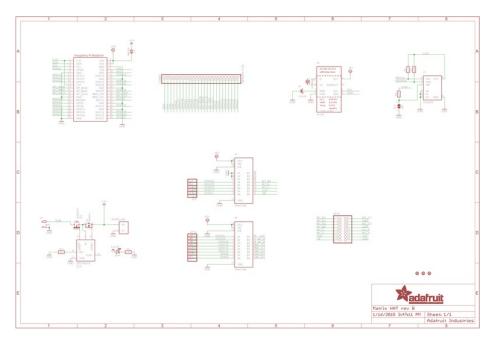
Downloads

Datasheets

- DS1307 Real Time Clock (https://adafru.it/em5)
- MAX4866 5V protection chip (https://adafru.it/em6)
- Fritzing object in the Adafruit Fritzing Library (https://adafru.it/aP3)
- EagleCAD PCB files on GitHub (https://adafru.it/qHc)

Schematic

Click to embiggen



Fabrication Print

Here's the fabrication print with dimensions in inches. This HAT is compatible with the Raspberry Pi mechanical HAT specification!

