Seeed Technology Co.,Ltd.

MR60BHA2

Breathing and Heartbeat Module Technical Specification (Beta Version)

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Table of contents

1. PRODUCT INTRODUCTION	3
2. PRODUCT FEATURES	3
3. APPLICATION SCENARIO	3
4. ELECTRICAL CHARACTERISTICS AND PARAMETERS	3
4.1 FUNCTION PARAMETERS	3
4.2 ELECTRICAL CHARACTERISTICS	4
4.3 RF CHARACTERISTICS	4
5.HARDWARE DESCRIPTION	5
5.1 OVERALL DIMENSIONS	5
5.2 PIN DEFINITION	6
5.3 MODULE PERIPHERAL REFERENCE DESIGN	7
5.4 STARTUP CONFIGURATION	7
6.USE AND CONFIGURATION	7
6.1 TYPICAL APPLICATION CIRCUIT	7
6.2 GUI VISUALIZATION TOOL APPLICATION	8
6.3 Installation method and sensing range	9
7. NOTE	10
8.RADAR RADOME DESIGN	10



1. Product Introduction

MR60BHA2 is a radar sensing module developed based on the ADT6101P chip. It monolithically integrates a 57~64GHz radio frequency transceiver system, 2T2R PCB microstrip antenna, 1MB flash, radar signal processing unit, and ARM® Cortex®-M3 core. This module is based on the FMCW radar mechanism, detects the radar echo reflected by the human body surface, and combines the radar signal processing algorithm to measure the respiratory heart rate frequency of people in specific situations.

2. Product Characteristics

- > Radar detection based on FMCW frequency modulated continuous wave signal
- > Realize contactless sensing of human breathing and heart rate
- > The maximum detection distance of human respiratory heart rate is 1.5m
- Universal UART interface, providing communication protocol
- > Multiple sets of IO ports and various communication interfaces are reserved to support secondary development by customers and are suitable for multiple scenarios.
- > Small size, only 25*31.5mm, supports pin header connection and patch connection.
- > Not affected by temperature, humidity, noise, airflow, dust, light and other environmental influences

3. Application Scenarios

♦ Smart home applications

Realize home empowerment based on breathing and heart rate measurement

health management

Real-time monitoring of respiratory and heart rate data

4. Electrical Characteristics and Parameters

4.1 Function parameters

parameter	minimum	Typical	maximum	unit
	value	value	value	
Breathing and heartbeat detection	0.4		1.5	m
distance (chest)				
Breath measurement accuracy		90		%



Breath measurement range			times/min
			ute
Heartbeat measurement accuracy	90)	%
Heartbeat measurement frequency			times/min
range			ute
refresh time			
Establish detection time	1		Min

4.2 Electrical characteristics

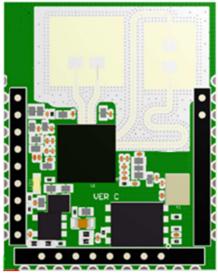
Working parameters	minimum	Typical	maximum	unit
	value	value	value	
Operating voltage (VCC)	3.1	3.3	3.5	V
Operating current (ICC)			600	mA
Operating temperature (TOP)	-20		85	°C
Storage temperature (TST)	-40		85	℃

4.3 RF characteristics

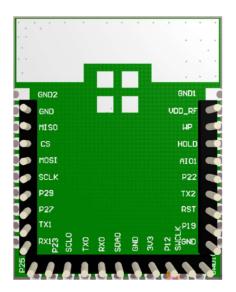
Working parameters	minimum	Typical	maximum	unit
	value	value	value	
working frequency	58		62	GHZ
Transmit power (Pout)		12		dBm
Antenna gain		4		dBi
Horizontal beam (-3dB)	-60		+60	0
Vertical beam (-3dB)	-60		+60	0

5. Hardware description

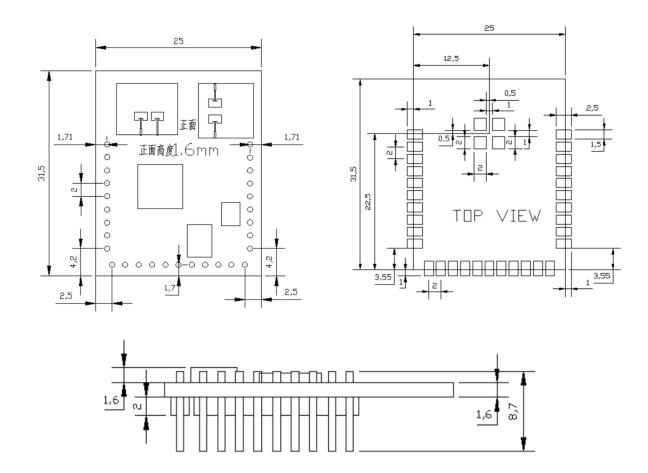
5.1 Dimensions



Module physical front view



Module physical rear view



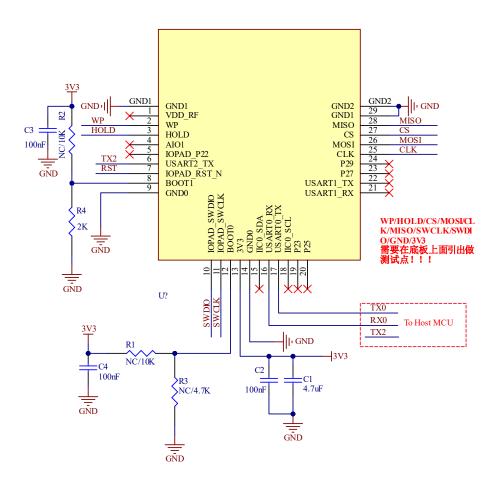


5.2 Pin definition

Pin name	describe	Remark
GND	GND	Only supports patch packaging
VDDRF	External RF Power /1.35V	
WP	Write protection active low	Flash function pin
HOLD	To pause the device without deselecting	Flash function pin
	the device	
AIO1	Temperature index test interface	Can be used as analog input
P22	interfaceGPIO_P22/LDO_EXT_EN_H	
TX2	GPIO_P20/uart2 txd	Control output (such as relay, etc.)
RST	Reset Signal input	
P19	GPIO_P19/boot1	Boot
GND0	GND	
SWDIO	SWD Debug Signal	
SWCLK	SWD Debug Clock	
P12	GPIO_P12/boot0	
3.3V	POWER INPUT 3.3V	
GND	GND	
SDA	GPIO_P08/IIC0_SDA	
RX0	GPIO_P01/uart0 _txd	
TX0	GPIO_P00/uart0 _txd	
SCL	GPIO_P07/IIC0_SCL	
P23	IOPAD_P23	
P25	IOPAD_P25	
RX1	GPIO_P11/uart1 rxd	
TX1	GPIO_P10/uart1 txd	
P27	IOPAD_P27	
P29	IOPAD_P29	
SCLK	IOPAD_P03/SPI0_SCLK	Can be used as RF ADC signal acquisition output terminal
MOSI	IOPAD_P06/SPI0_MOSI	Can be used as RF ADC signal acquisition output terminal
CS	IOPAD_P04/SPI0_CS	Can be used as RF ADC signal acquisition output terminal
MISO	IOPAD_P05/SPI0_MISO	
GND1	GND	
GND2	GND	Only supports patch packaging
	GND VDDRF WP HOLD AIO1 P22 TX2 RST P19 GND0 SWDIO SWCLK P12 3.3V GND SDA RX0 TX0 SCL P23 P25 RX1 TX1 P27 P29 SCLK MOSI CS MISO GND1	GND GND VDDRF External RF Power /1.35V WP Write protection active low HOLD To pause the device without deselecting the device AIO1 Temperature index test interface P22 interfaceGPIO_P22/LDO_EXT_EN_H TX2 GPIO_P20/uart2 txd RST Reset Signal input P19 GPIO_P19/boot1 GNDO GND SWD Debug Signal SWCLK SWD Debug Clock P12 GPIO_P12/boot0 3.3V POWER INPUT 3.3V GND GND SDA GPIO_P08/IICO_SDA RX0 GPIO_P01/uart0_txd TX0 GPIO_P00/uart0_txd SCL GPIO_P07/IICO_SCL P23 IOPAD_P23 P25 IOPAD_P25 RX1 GPIO_P11/uart1 rxd TX1 GPIO_P11/uart1 rxd TX1 GPIO_P10/uart1 txd P27 IOPAD_P27 P29 IOPAD_P29 SCLK IOPAD_P06/SPI0_MOSI CS IOPAD_P06/SPI0_MISO GND1 GND GND GND CS IOPAD_P05/SPIO_MISO GND1 GND



5.3 Module peripheral reference design



5.4 Startup configuration

BOOT1	воото	Start mode	Remark
0	0	UART1	Serial port 1 starts
0	1	Flash Flash startup in modu	
1	0	1100	This module does not
'	0	IIC0	support this method
1	1	Debug For software debugg	

6.Use and Configuration

6.1 Typical application circuit

The MR60BHA2 module can directly use UART0 to output detection results according to the specified protocol. The serial port data includes total phase, respiratory phase, heartbeat phase results, respiratory rate, and heartbeat rate results. Users can use it flexibly according to specific application scenarios.

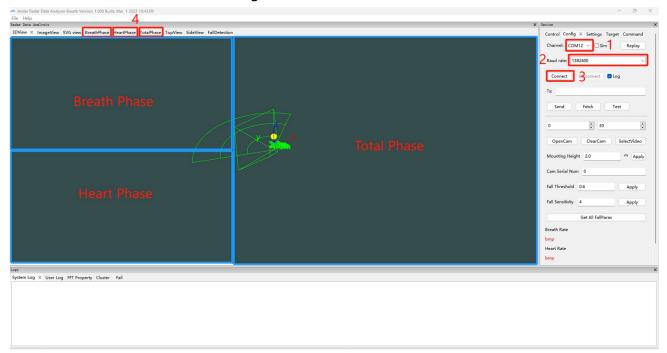


The module supplies 3.3V power supply, and the input power supply capacity is required to be greater than 1A.

The module IO port output voltage is 3.3V. The default baud rate of the serial port is 1382400, with no parity check.

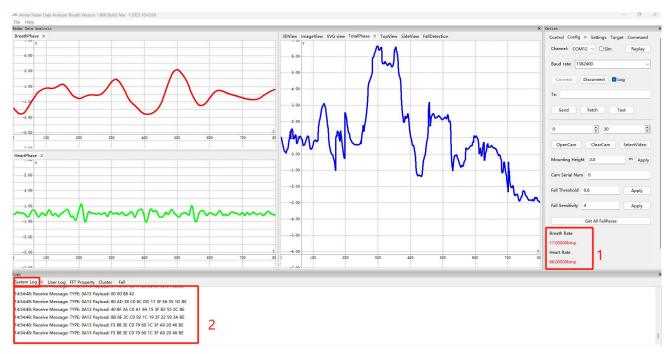
6.2 GUI visualization tool application

- 1. Device connection
- 1) Select the connected serial port in the Config interface in the Option bar on the upper right
 - 2) Set the baud rate to 115200
 - 3) Click the [Connect] button to start measurement
- 4) To facilitate viewing of data, you can drag and drop the Breath Phase, Heart Phase, and Total Phase windows into the following format



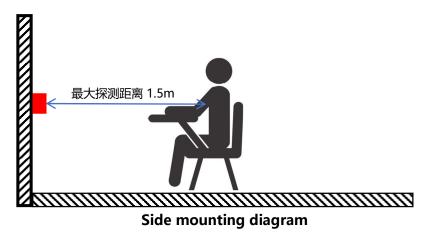
- 2. Data view
- 1) The lower right corner displays breathing and heart rate information.
- 2) The [System Log] window in the lower left corner displays message information, which includes total phase data, heartbeat phase, respiratory phase, respiratory rate, and heartbeat rate information.





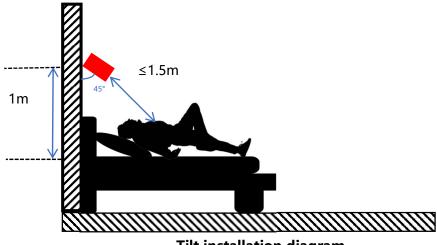
6.3 Installation method and sensing range

1. Side-mounted, it is recommended that the radar installation height be consistent with the chest height of the person being measured, and the module position and chest position ≤ 1.5m



2. Inclined installation. For sleep breathing and heart rate detection needs, an inclined installation method can be adopted. The radar is required to be installed at a height of 1m directly above the head of the bed, tilted downward at 45 ° towards the middle of the bed, and the distance between the radar and the chest cavity is controlled to be within 1.5m. The radar The normal direction is aligned with the main detection position to ensure that the radar can detect respiratory and heartbeat data.





Tilt installation diagram

7. Precautions

- 1. The detection range of the radar module is closely related to the target RCS and environmental factors. The effective detection range may change as the environment and target change. Therefore, it is normal for the effective detection range to fluctuate within a certain range.
- 2. The radar module has extremely high power requirements, requiring an input voltage of 3.2~3.4V, power supply ripple \leq 50mV, and current \geq 1A. If a DCDC power supply is used, the switching frequency is required to be no less than 2MHZ.
- 3. Since respiratory and heart rate are weak reflection signals, radar signal processing requires a period of data accumulation. During the accumulation process, there are many factors that affect the radar processing results, so sporadic detection failures are normal.
- 4. Currently, respiratory and heart rate measurement only supports one person. Please make sure there is only one person in the detection area.
- 5. Measurement is required in a resting state, and measurement will be stopped if large movements are detected.

8. Radar radome design

Radomes are used to protect radar antennas from external environmental influences such as rain, sunlight, wind, etc. However, it has the following effects on the radar antenna: the dielectric loss and reflection loss caused by the radome will reduce the effective power of the radar; it will cause the antenna beam to be distorted, causing the radar's area of action to change; the reflection of electromagnetic waves by the shell will cause the radar transmitting and receiving antenna to The isolation becomes worse and may cause receiver saturation; the phase of electromagnetic waves changes when they pass through the radar radome, affecting the angle measurement. Therefore, it is



necessary to design the radar radome to reduce the impact of the shell and improve the radar performance.

Design requirements:

1. When selecting the material of the radome, under the premise of ensuring the sturdiness and low cost, materials with smaller dielectric constant and loss tangent should be selected to reduce the impact of the radome on radar performance.

The dielectric constant and dissipation factor of commonly used materials are as follows:

Material	Dielectric constant ($\varepsilon_{ m r}$)	Dissipation factor (tan δ)
polycarbonate	2.9	0.012
ABS	2.0-3.5	0.0050-0.019
PEEK	3.2	0.0048
PTFE (Teflon®)	2	<0.0002
Plexiglass ®	2.6	0.009
Glass	5.75	0.003
ceramics	9.8	0.0005
PE	2.3	0.0003
PBT	2.9-4.0	0.002

- 2. The radar radome is required to have a smooth surface and uniform thickness.
- 3. Radar radome thickness design requirements

$$T = N \bullet \frac{c}{2f\sqrt{\mathcal{E}_r}}$$
 , N=1, 2, 3 ...

T: radome thickness

c: speed of light, 3×10^8 m/s;

f: center frequency

 \mathcal{E}_r : Material dielectric constant, DK

4. Design requirements for the height of the radar antenna from the inner surface of the housing

$$d = N \bullet \frac{c}{2 f} N=1, 2, 3 ...$$

c: speed of light, 3×10^8 m/s;

f: center frequency

f=60GHz

c/2f=2.5mm



Revision History

Revison	Release Date	Description
V1.0	2024/03/05	Initial version

