



ED-IPC2600 Series

High Reliability Industrial Computer Based On Raspberry Pi CM4

User Manual

EDA Technology Co., LTD

December 2023

Contact Us

Thank you very much for purchasing and using our products, and we will serve you wholeheartedly.

As one of the global design partners of Raspberry Pi, we are committed to providing hardware solutions for IOT, industrial control, automation, green energy and artificial intelligence based on Raspberry Pi technology platform.

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Foreword

Related Manuals

All kinds of product documents contained in the product are shown in the following table, and users can choose to view the corresponding documents according to their needs.

Documents	Instruction
ED-IPC2600 Series Datasheet	This document introduces the product features, software and hardware specifications, dimensions and ordering code of ED-IPC2600 series to help users understand the overall system parameters of the products.
ED-IPC2600 Series User Manual	This document introduces the appearance, installation, startup and configuration of ED-IPC2600 series to help users use the product better.
ED-IPC2600 Series Application Guide	This document introduces the OS download, eMMC flashing and partial configuration of ED-IPC2600 series to help users use the product better.

Users can visit the following website for more information:

<https://www.edatec.cn>

Reader Scope

This manual is applicable to the following readers:

- ◆ Mechanical Engineer
- ◆ Electrical Engineer
- ◆ Software Engineer
- ◆ System Engineer

Related Agreement

Terminology Convention

Terminology	Meaning
CM4	Raspberry Pi Compute Module 4

Symbolic Convention

Symbolic	Instruction
	Prompt symbols, indicating important features or operations.
	Notice symbols, which may cause personal injury, system damage, or signal interruption/loss.
	May cause great harm to people.

Safety Instructions

- ◆ This product should be used in an environment that meets the requirements of design specifications, otherwise it may cause failure, and functional abnormality or component damage caused by non-compliance with relevant regulations are not within the product quality assurance scope.
- ◆ Our company will not bear any legal responsibility for personal safety accidents and property losses caused by illegal operation of products.
- ◆ Please do not modify the equipment without permission, which may cause equipment failure.
- ◆ When installing equipment, it is necessary to fix the equipment to prevent it from falling.
- ◆ If the equipment is equipped with an antenna, please keep a distance of at least 20cm from the equipment during use.
- ◆ Do not use liquid cleaning equipment, and keep away from liquids and flammable materials.
- ◆ This product is only supported for indoor use.

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1 Product Description

This chapter introduces the product overview, packing list, appearance, button, indicators and interfaces.

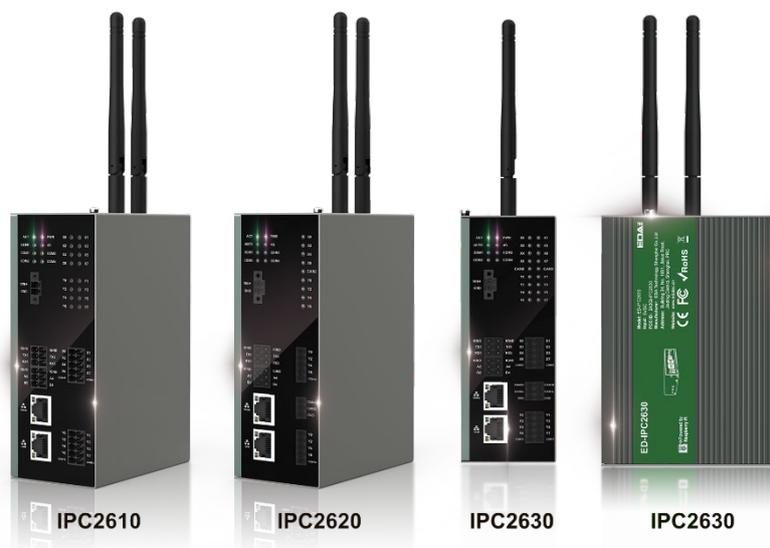
- ✓ Overview
- ✓ Packing List
- ✓ Appearance
- ✓ Button
- ✓ Indicator
- ✓ Interface

1.1 Overview

ED-IPC2600 series is a highly reliable industrial computer based on Raspberry Pi CM4. According to different application scenarios and user needs, different specifications of RAM and eMMC computer systems can be selected.

- ◆ RAM can choose 1GB、2GB、4GB and 8GB
- ◆ eMMC can choose 8GB、16GB and 32GB

ED-IPC2600 series includes three models: ED-IPC2610, ED-IPC2620 and ED-IPC2630, which provides common interfaces such as HDMI, USB, Ethernet, RS232, RS485, DI, DO and CAN. ED-IPC2600 series support access to the network through Wi-Fi, Ethernet and 4G. The integration of super capacitor (backup power supply, which is optional), RTC, Watch Dog, EEPROM and encryption chip provides the ease of use and reliability of the product, which is mainly used in industrial control and IOT.



1.2 Packing List

- ◆ 1x ED-IPC2600 Unit (with DIN-rail bracket)
- ◆ **[option Wi-Fi/BT version]** 1x 2.4GHz/5GHz Wi-Fi/BT Antenna
- ◆ **[option 4G version]** 1x 4G/LTE Antenna

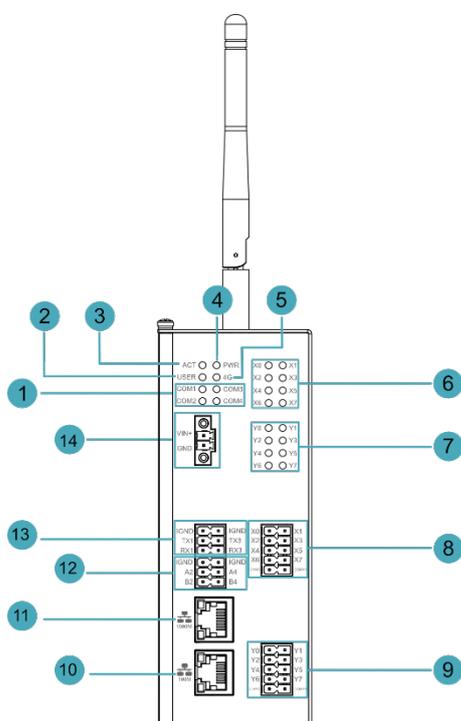
1.3 Appearance

Introducing the functions and definitions of interfaces on each panel.

1.3.1 Front Panel

Introducing the front panel interface types and definitions.

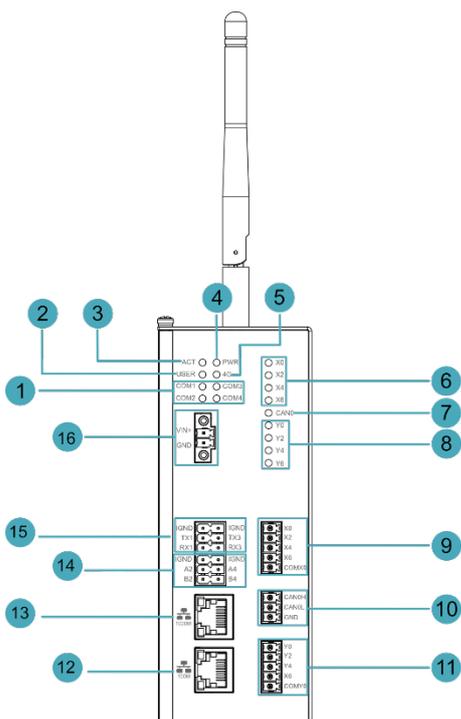
ED-IPC2610



NO.	Function Definition
1	4 x green UART indicators, which is used to check the communication status of UART port.
2	1 x green user indicator, user can customize a status according to actual application.
3	1 x green system status indicator, which is used to check the working status of device.
4	1 x red power indicator, which is used to check the status of device power-on and power-off.
5	1 x green 4G indicator, which is used to check the status of 4G signal.
6	8 x green DI indicators, which is used to check the communication status of DI signal.
7	8 x green DO indicators, which is used to check the communication status of DO signal.
8	8 x DI ports, 10-Pin 3.5mm spacing phoenix terminals, which is used to connect third-

NO.	Function Definition
	party sensors.
9	8 x DO ports, 10-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party load.
10	1 x 10/100M adaptive ethernet port, RJ45 connector, with led indicator. It can be used to access the network.
11	1 x 10/100/1000M adaptive ethernet port, RJ45 connector, with led indicator. It can be used to access the network. PoE can be supported through expansion module.
12	2 x RS485 ports, 6-Pin 3.5mm spacing phoenix terminal, which is used to connect the third-party control equipment.
13	2 x RS232 ports, 6-Pin 3.5mm spacing phoenix terminal, which is used to connect the third-party control equipment.
14	1 x DC input, 2-Pin 3.5mm spacing phoenix terminals with screw holes. It supports 9V~36V input, the signal is defined as VIN+/GND.

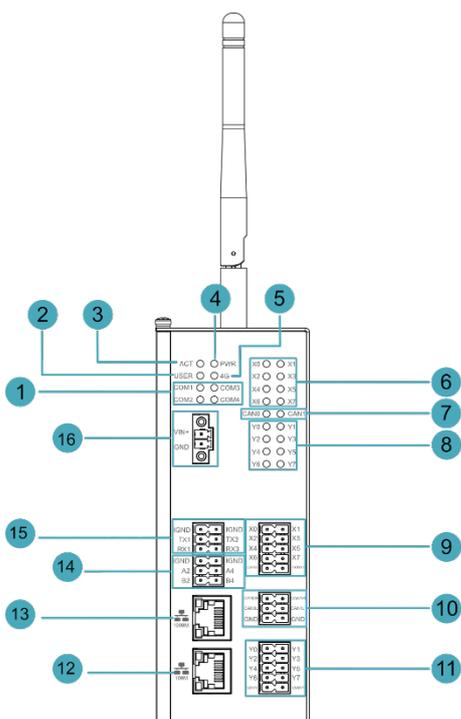
ED-IPC2620



NO.	Function Definition
1	4 x green UART indicators, which is used to check the communication status of UART port.
2	1 x green user indicator, user can customize a status according to actual application.
3	1 x green system status indicator, which is used to check the working status of device.
4	1 x red power indicator, which is used to check the status of device power-on and power-off.

NO.	Function Definition
5	1 x green 4G indicator, which is used to check the status of 4G signal.
6	4 x green DI indicators, which is used to check the communication status of DI signal.
7	1 x CAN indicator, which is used to check the communication status of CAN signal.
8	4 x green DO indicators, which is used to check the communication status of DO signal.
9	4 x DI ports, 5-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party sensors.
10	1 x CAN port, 3-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party control equipment.
11	4 x DO ports, 5-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party load.
12	1 x 10/100M adaptive ethernet port, RJ45 connector, with led indicator. It can be used to access the network.
13	1 x 10/100/1000M adaptive ethernet port, RJ45 connector, with led indicator. It can be used to access the network. PoE can be supported through expansion module.
14	2 x RS485 ports, 6-Pin 3.5mm spacing phoenix terminal, which is used to connect the third-party control equipment.
15	2 x RS232 ports, 6-Pin 3.5mm spacing phoenix terminal, which is used to connect the third-party control equipment.
16	1 x DC input, 2-Pin 3.5mm spacing phoenix terminals with screw holes. It supports 9V~36V input, the signal is defined as VIN+/GND.

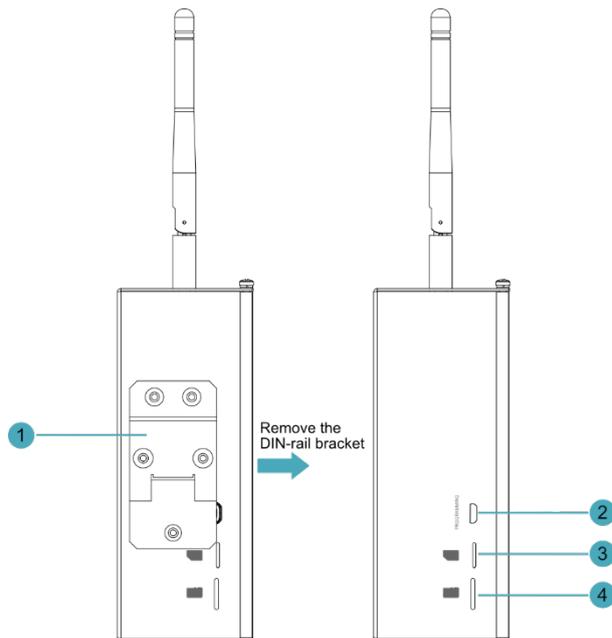
ED-IPC2630



NO.	Function Definition
1	4 x green UART indicators, which is used to check the communication status of UART port.
2	1 x green user indicator, user can customize a status according to actual application.
3	1 x green system status indicator, which is used to check the working status of device.
4	1 x red power indicator, which is used to check the status of device power-on and power-off.
5	1 x green 4G indicator, which is used to check the status of 4G signal.
6	8 x green DI indicators, which is used to check the communication status of DI signal.
7	2 x CAN indicators, which is used to check the communication status of CAN signal.
8	8 x green DO indicators, which is used to check the communication status of DO signal.
9	8 x DI ports, 10-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party sensors.
10	2 x CAN ports, 6-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party control equipment.
11	8 x DO ports, 10-Pin 3.5mm spacing phoenix terminals, which is used to connect third-party load.
12	1 x 10/100M adaptive ethernet port, RJ45 connector, with led indicator. It can be used to access the network.
13	1 x 10/100/1000M adaptive ethernet port, RJ45 connector, with led indicator. It can be used to access the network. PoE can be supported through expansion module.
14	2 x RS485 ports, 6-Pin 3.5mm spacing phoenix terminal, which is used to connect the third-party control equipment.
15	2 x RS232 ports, 6-Pin 3.5mm spacing phoenix terminal, which is used to connect the third-party control equipment.
16	1 x DC input, 2-Pin 3.5mm spacing phoenix terminals with screw holes. It supports 9V~36V input, the signal is defined as VIN+/GND.

1.3.2 Rear Panel

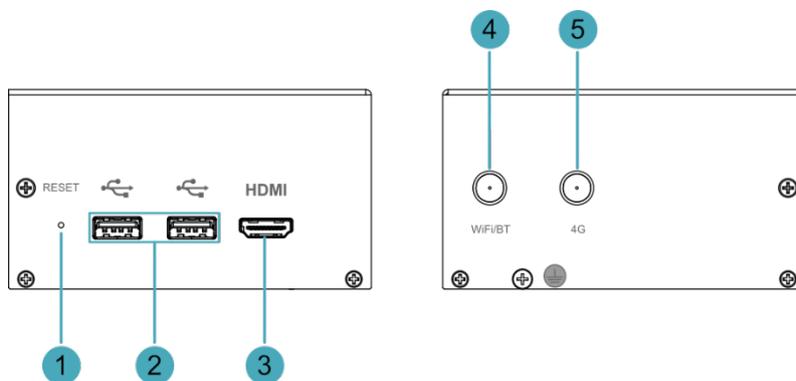
Introducing the types and definitions of the rear panel interface.



NO.	Function Definition
1	1 x DIN-rail bracket, install ED-IPC2600 Unit on the DIN-rail through the bracket.
2	1 x Micro-SD card slot, it supports the installation of SD card for storing user data.
3	1 x Nano SIM slot, uses to install a SIM card for acquiring 4G signals.
4	1 x Micro USB port, it supports to flash eMMC for the system.

1.3.3 Side Panel

Introducing the types and definitions of side panel interfaces.



NO.	Function Definition
1	1 x Reset button, hidden button, press the button to restart the device.
2	2 x USB 2.0 ports, type A connector, each channel supports up to 480Mbps.
3	1 x HDMI port, type A connector, which compatibles with HDMI2.1 standard and supports 4K 60Hz. It supports to connect a displayer.
4	1 x Wi-Fi/BT antenna port(optional), SMA connector, which can connect to Wi-Fi/BT antenna.
5	1 x 4G antenna port(optional), SMA connector, which can connect to 4G antenna.

1.4 Button

ED-IPC2600 series device includes a RESET button, which is a hidden button, and the silkscreen on the case is "RESET". Pressing the RESET button will reset the device.

1.5 Indicator

Introducing the various statuses and meanings of indicators contained in ED-IPC2600 series device.

Indicator	Status	Description
PWR	On	The device has been powered on.
	Blink	Power supply of the device is abnormal, please stop the power supply immediately.
	Off	The device is not powered on.
ACT	Blink	The system started successfully and is reading and writing data.
	Off	The device is not powered on or does not read and write data.
USER	On	User can customize a status according to actual application.
	Off	The device is not powered on or not defined by the user, and the default status is off.
4G	On	The dial-up is successful and the connection is normal.
	Off	4G signal is not connected or the device is not powered on.
Yellow indicator of Ethernet port	On	The data transmission is abnormal.
	Blink	Data is being transmitted over the Ethernet port.
	Off	The Ethernet connection is not set up.
Green indicator of Ethernet port	On	The Ethernet connection is in the normal state.
	Blink	The Ethernet connection is abnormal.
	Off	The Ethernet connection is not set up.
COM1~COM4	On/Blink	Data is being transmitted.
	Off	The device is not powered on or there is no data transmission.
X0~X7	On/Blink	The input signal has been detected.
	Off	The device is not powered on or there is no data transmission.
CAN0~CAN1	On/Blink	Data is being transmitted.
	Off	The device is not powered on or there is no data transmission.
Y0~X7	On/Blink	The output signal has been detected.
	Off	The device is not powered on or there is no data transmission.

1.6 Interface

Introducing the definition and function of each interface in the product.

1.6.1 Card Slot

ED-IPC2600 series device includes an SD card slot and a Nano SIM card slot.

1.6.1.1 SD Card Slot

The silkscreen on the case of Micro SD card slot is "", which is used to install SD card for storing user data.

1.6.1.2 SIM Card Slot (optional)

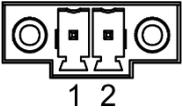
The silkscreen on the case of Nano SIM card slot is "", which is used to install SIM card for obtaining 4G signals.

The size differences between standard SIM, Micro SIM and Nano SIM cards are as follows:



1.6.2 Power Supply Interface

The ED-IPC2600 series device includes one power input, 2-Pin 3.5mm spacing phoenix terminals with screw holes. The silkscreen of port is "VIN+/GND", and the pins are defined as follows.

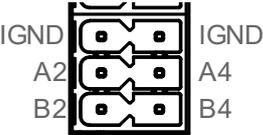
	Pin ID	Pin Name
	1	GND
	2	9V~36V

1.6.3 RS485 Interface

ED-IPC2600 series equipment includes 2 RS485 ports, 6-Pin 3.5mm spacing phoenix terminals. The silkscreen of single RS485 is "IGND/A/B".

Pin Definition

Terminal pins are defined as follows:

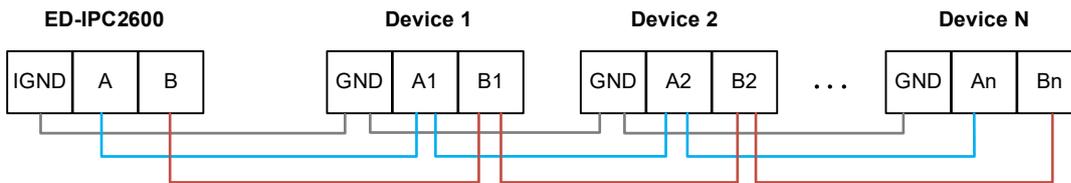
	Pin ID	Pin Name
	1	RS485-2_B
	2	RS485-4_B
	3	RS485-2_A
	4	RS485-4_A
	5	GND
	6	GND

The pin names of CM4 corresponding to RS485 interface are as follows:

Signal	CM4 GPIO Name	CM4 Pin Out
RS485-2_B	GPIO13	UART5_RXD
RS485-4_B	GPIO9	UART4_RXD
RS485-2_A	GPIO12	UART5_TXD
RS485-4_A	GPIO8	UART4_TXD

Connecting Cables

Schematic diagram of RS485 wires is as follows:



RS485 Terminal Resistor

ED-IPC2600 contains 2 RS485 ports. A 120R jumper resistor is reserved between A and B of each RS485 line. The jumper cap can be inserted to enable the jumper resistor. By default, the jumper cap is not connected, and the 120R termination resistor function is disabled.

The position of the 120Ω terminal resistor of the 2 RS485 in the PCBA and the relationship between the RS485 ports and corresponding COM ports are shown in the table below.

Location in PCBA	Corresponding COM port	The specific location of the corresponding COM
J22	COM2	
J24	COM4	

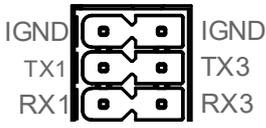
1.6.4 RS232 Interface

ED-IPC2600 contains 2 RS232 ports, 6-Pin 3.5mm spacing phoenix terminals.

The silkscreen of single RS232 is "IGND/TX/RX".

Pin Definition

Terminal pins are defined as follows:

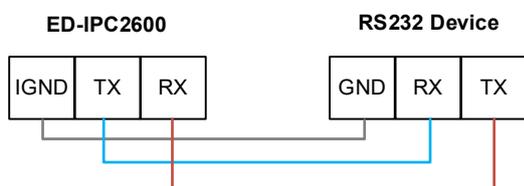
	Pin ID	Pin Name
	1	RS232-1_RX
	2	RS232-3_RX
	3	RS232-1_TX
	4	RS232-3_TX
	5	GND
	6	GND

The pin names of CM4 corresponding to RS232 interface are as follows:

Signal	CM4 GPIO Name	CM4 Pin Out
RS232-1_RX	GPIO5	UART3_RXD
RS232-3_RX	GPIO1	UART2_RXD
RS232-1_TX	GPIO4	UART3_TXD
RS232-3_TX	GPIO0	UART2_TXD

Connecting Cables

Schematic diagram of RS232 wires is as follows:



1.6.5 DI Interface

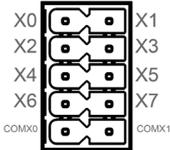
ED-IPC2600 contains 4 or 8 DI ports. Different product models correspond to different numbers of DI ports:

- ◆ ED-IPC2610: 8 x DI
- ◆ ED-IPC2620: 4 x DI
- ◆ ED-IPC2630: 8 x DI

Every 4 DI share one common pin (called COM): X0, X2, X4 and X6 share COMX0; X1, X3, X5 and X7 share COMX1.

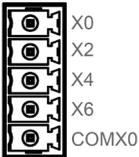
Pin Definition-ED-IPC2610&ED-IPC2630

Terminal pins are defined as follows:

	Pin ID	Pin Name
	1	X0
	2	X1
	3	X2
	4	X3
	5	X4
	6	X5
	7	X6
	8	X7
	9	COMX0
10	COMX1	

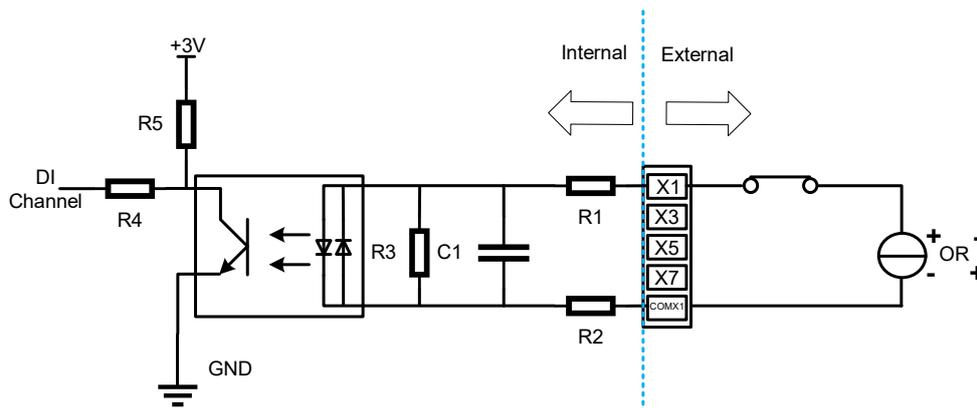
Pin Definition -ED-IPC2620

Terminal pins are defined as follows:

	Pin ID	Pin Name
	1	X0
	2	X2
	3	X4
	4	X6
5	COMX0	

Connecting Cables

Schematic diagram of a single DI wire is as follows:



Parameter	Description
Input Type	NPN & PNP
Isolation Protection	5 kV
COM	Every 4 DI share one common pin (called COM): <ul style="list-style-type: none"> • X0, X2, X4 and X6 share COMX0 • X1, X3, X5 and X7 share COMX1
DI to COM	<ul style="list-style-type: none"> • ON state: 5~30 VDC • OFF state: 0~2 VDC

1.6.6 DO Interface

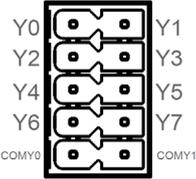
ED-IPC2600 contains 4 or 8 DO ports. Different product models correspond to different numbers of DO ports:

- ◆ ED-IPC2610: 8 x DO
- ◆ ED-IPC2620: 4 x DO
- ◆ ED-IPC2630: 8 x DO

Every 4 DO share one common pin (called COM): Y0, Y2, Y4 and Y6 share COMY0; Y1, Y3, Y5 and Y7 share COMY1.

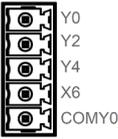
Pin Definition -ED-IPC2610&ED-IPC2630

Terminal pins are defined as follows:

	Pin ID	Pin Name
	1	Y0
	2	Y1
	3	Y2
	4	Y3
	5	Y4
	6	Y5
	7	Y6
	8	Y7
	9	COMY0
	10	COMY1

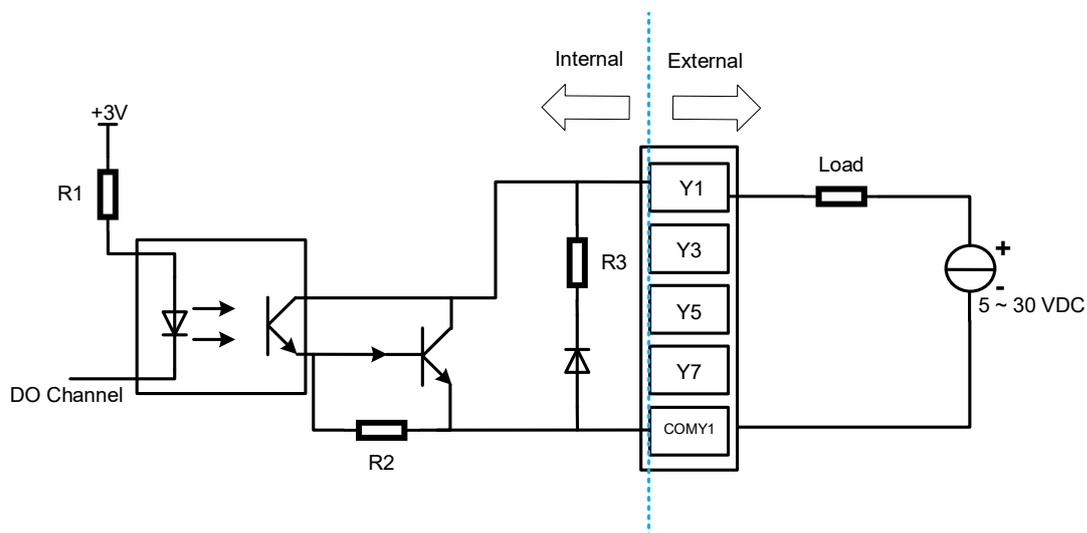
Pin Definition -ED-IPC2620

Terminal pins are defined as follows:

	Pin ID	Pin Name
	1	Y0
	2	Y2
	3	Y4
	4	Y6
	5	COMY0

Connecting Cables

Schematic diagram of a single DO wire is as follows:



Parameter	Description
Output Type	Transistor
Isolation Protection	5 kV
COM	Every 4 DI share one common pin (called COM): <ul style="list-style-type: none"> • Y0, Y2, Y4 and Y6 share COMY0 • Y1, Y3, Y5 and Y7 share COMY1
Output	5~30 VDC (24 VDC is recommended), maximum current is 1.5A (per channel)

1.6.7 CAN Interface

ED-IPC2600 contains 0 ~ 2 CAN ports. Different product models correspond to different numbers of CAN ports:

- ◆ ED-IPC2610: Without CAN
- ◆ ED-IPC2620: 1 x CAN
- ◆ ED-IPC2630: 2 x CAN

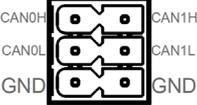
Pin Definition-ED-IPC2620

Terminal pins are defined as follows:

	Pin ID	Pin Name
	1	CAN0H
	2	CAN0L
3	GND	

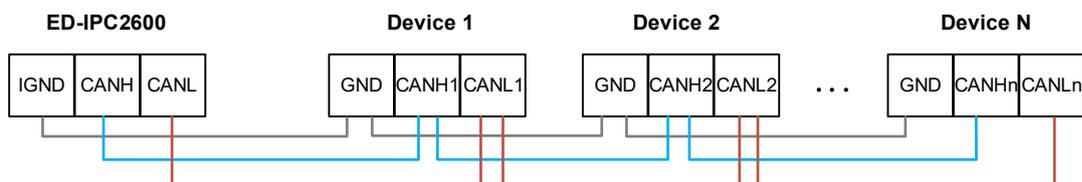
Pin Definition -ED-IPC2630

Terminal pins are defined as follows:

	Pin ID	Pin Name
	1	CAN0H
	2	CAN1H
	3	CAN0L
	4	CAN1L
	5	GND
6	GND	

Connecting Cables

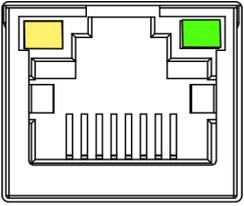
Schematic diagram of CAN wires is as follows:



1.6.8 1000M Ethernet Interface

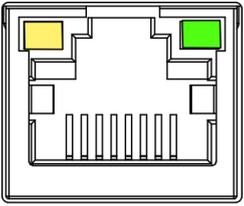
ED-IPC2600 device includes one adaptive 10/100/1000M Ethernet port, and the silkscreen is .

The connector is RJ45, which can support PoE with the expansion module. When accessing to network, it is recommended to use the network cable of Cat6 and above. The pins corresponding to the terminal are defined as follows:

	Pin ID	Pin Name
	1	TX4-
	2	TX4+
	3	TX3-
	4	TX3+
	5	TX2-
	6	TX2+
	7	TX1-
8	TX1+	

1.6.9 100M Ethernet Interface

ED-IPC2600 device includes an adaptive 10/100M Ethernet port, and the silkscreen is . The connector is RJ45, and it is recommended to use the network cable with Cat6 and above when accessing to network. The pins corresponding to the terminal are defined as follows:

	Pin ID	Pin Name
	1	-
	2	-
	3	Rx-
	4	-
	5	-
	6	Rx+
	7	Rx--
8	Rx+	

1.6.10 HDMI Interface

ED-IPC2600 series device includes one HDMI port, the silkscreen is "**HDMI**". The connector is type A HDMI, which can connect to an HDMI display and supports up to 4Kp60.

1.6.11 USB 2.0 Interface

ED-IPC2600 series device includes 2 USB2.0 ports, the silkscreen is "". The connector is type A USB, which can connect to standard USB 2.0 peripherals and supports up to 480Mbps.

1.6.12 Micro USB Interface

ED-IPC2600 series device includes one Micro USB interface, the silkscreen is "DOWNLOAD" and it can be connected to a PC to flash eMMC of the device.

1.6.13 Antenna Interface(optional)

The ED-IPC2600 contains up to 2 SMA antenna ports, the silkscreens are "4G" and "Wi-Fi/BT". They can be connected to the 4G antenna and Wi-Fi/BT antenna.

2 Installing Components

This chapter describes how to install components.

- ✓ Install Antenna (optional)
- ✓ Install Micro SD Card
- ✓ Install Nano SIM Card (optional)

2.1 Install Antenna (optional)

If the selected ED-IPC2600 series device includes 4G and Wi-Fi functions, the antenna need to be installed before using the device.

Preparation:

The corresponding antennas have been obtained from the packaging box. If there are multiple antennas, they can be distinguished by the labels on the antennas.

Steps:

1. Locate the antenna port where the antenna is to be installed, as shown in the red box in the figure below.



2. Align the ports on both sides of the device and the antenna, then tighten them clockwise to ensure that they will not fall off.

2.2 Install Micro SD Card

Preparation:

The Micro SD card to be used has been obtained.

Steps:

1. Locate the Micro SD card slot where the Micro SD is to be installed, as shown in the red box below.



2. Insert the Micro SD card with the chip side up into the corresponding card slot, and hear a sound to indicate that the installation is complete.



2.3 Install Nano SIM Card (optional)

If the selected ED-IPC2600 series device includes 4G function, the SIM card need to be installed before using the device.

Preparation:

The 4G Nano SIM card to be used has been obtained.

Steps:

1. Locate the Nano SIM card slot where the Nano SIM card is to be installed, as shown in the red box below.



2. Insert the Nano SIM card with the chip side up into the corresponding card slot, and hear a sound to indicate that the installation is complete.



3 Installing Device

This chapter introduces how to install the device.

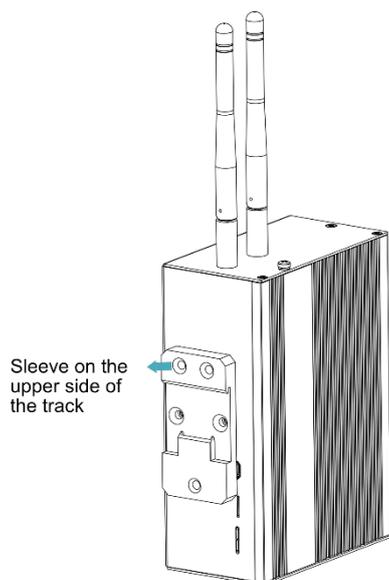
- ✓ DIN-Rail Installation

3.1 DIN-Rail Installation

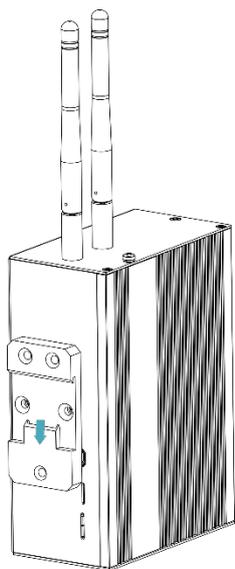
When the ED-IPC2600 series device leaves the factory, the DIN-rail bracket is installed as standard by default.

Steps:

1. Face the side of the DIN-rail bracket to the rail to be installed, and the upper side of the bracket is sleeved on the upper side of the rail.



2. Press down the buckle on the lower side of the DIN-rail bracket until the bracket can be buckled on the rail, and the installation is completed.



4 Booting The Device

This chapter introduces how to connect cables and boot the device.

- ✓ Connecting Cables
- ✓ Booting The System For The First Time

4.1 Connecting Cables

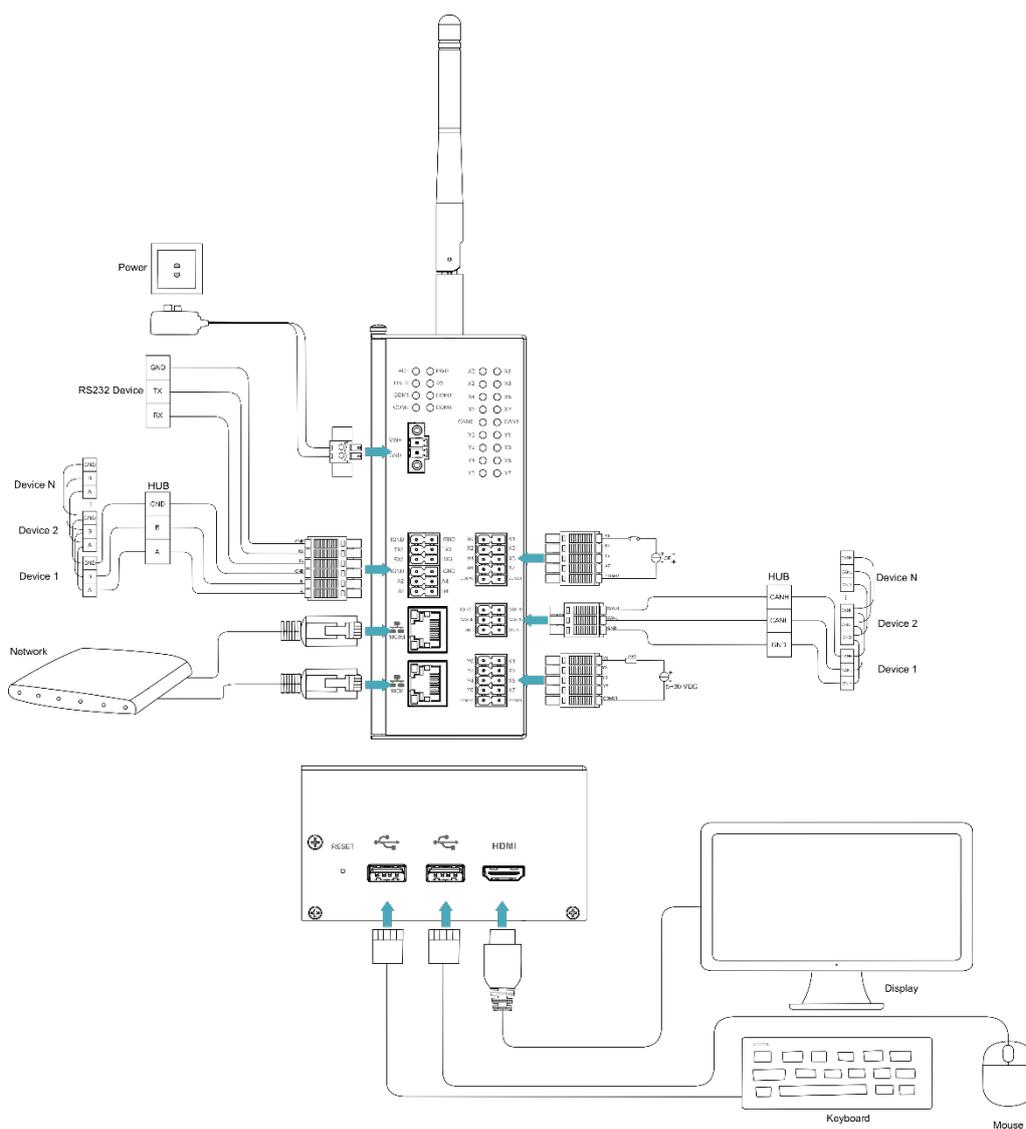
This section describes how to connect cables.

Preparation:

- ◆ Accessories such as display, mouse, keyboard and power adapter that can be used normally have been ready.
- ◆ A network that can be used normally.
- ◆ Get the HDMI cable and network cable that can be used normally.

Schematic diagram of connecting cables:

Please refer to [1.6 Interfaces](#) for the pin definition of each interface and the specific method of wiring.



4.2 Booting The System For The First Time

ED-IPC2600 series device has no switching power supply. After the power supply is connected, the system will start.

- ◆ The red PWR indicator is on, indicating that the device has been powered normally.
- ◆ The green ACT indicator is blinking, indicating that the system is started normally, and then the logo of Raspberry Pi will appear in the upper left corner of the screen.

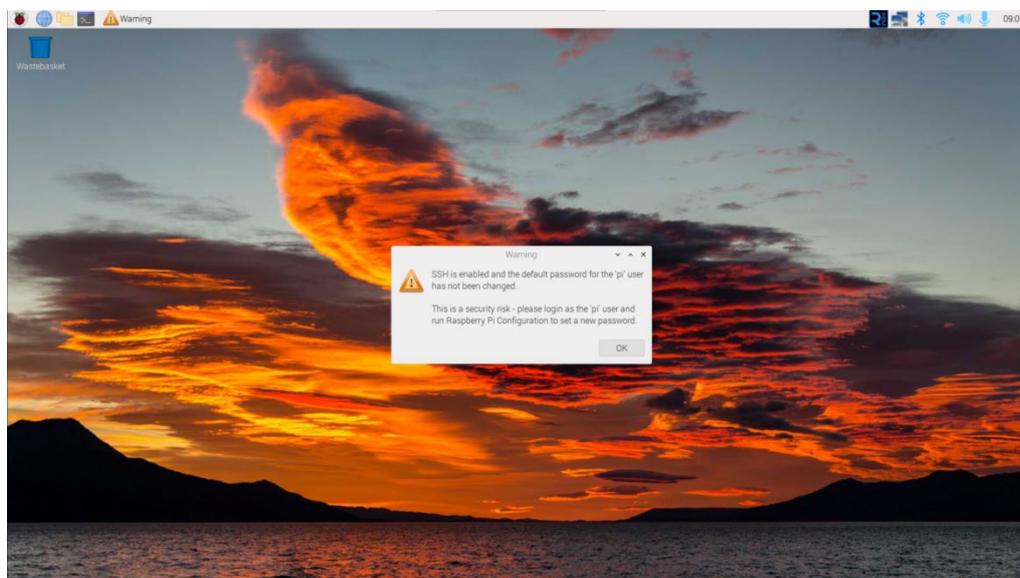


TIP:

Default username is pi, Default password is raspberry.

4.2.1 Raspberry Pi OS (Desktop)

If the Desktop version of the system is installed when the product leaves the factory, after the device is started, it will directly enter the desktop, as shown in the following figure.



4.2.2 Raspberry Pi OS (Lite)

If the Lite version of the system is installed at the factory, the default username pi will be used to automatically log in after the device is started, and the default password is raspberry. The following figure shows that the system has been started normally.

```
[ OK ] Started LSB: rng-tools (Debian variant).
[ OK ] Started WPA supplicant.
[ OK ] Started Authorization Manager.
[ OK ] Reached target Network.
[ OK ] Listening on Load/Save RF Kill Switch Status /dev/rfkill Watch.
Starting Modem Manager...
Starting /etc/rc.local Compatibility...
Starting Permit User Sessions...
[ OK ] Finished Remove Stale Onlimext4 Metadata Check Snapshots.
[ OK ] Started /etc/rc.local Compatibility.
Starting Load/Save RF Kill Switch Status...
[ OK ] Finished Permit User Sessions.
[ OK ] Started Getty on tty1.
[ OK ] Reached target Login Prompts.
[ OK ] Started Load/Save RF Kill Switch Status.
[ OK ] Started User Login Management.
Starting Save/Restore Sound Card State...
[ OK ] Finished Save/Restore Sound Card State.
[ OK ] Reached target Sound Card.
[ OK ] Started Modem Manager.
[ OK ] Started LSB: Switch to on= (unless shift key is pressed).

Raspbian GNU/Linux 11 raspberrypi tty1

raspberrypi login: pi
Password:
Linux raspberrypi 6.1.21-08+ #1642 SMP PREEMPT Mon Apr 3 17:24:16 BST 2023 aarch64

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Tue Jul 11 11:15:28 BST 2023 on tty1

Wi-Fi is currently blocked by rfkill.
Use raspi-config to set the country before use.

pi@raspberrypi:~$ ~
```

5 Configuring System

This chapter introduces how to configure system.

- ✓ Finding Device IP
- ✓ Remote Login
- ✓ Configuring Storage Devices
- ✓ Configuring Ethernet IP
- ✓ Configuring Wi-Fi (Optional)
- ✓ Configuring Bluetooth (optional)
- ✓ Configuring 4G (Optional)
- ✓ Configuring Buzzer
- ✓ Configuring RTC
- ✓ Configuring Serial Port
- ✓ Configuring DO Port
- ✓ Configuring CAN Port
- ✓ Configuring USER Indicator

5.1 Finding Device IP

In some application scenarios, it is necessary to remotely log in or manage devices, so it is necessary to obtain the device IP.

5.1.1 Query IP by Using ifconfig Command

After the device is started normally and the display is connected, you can use the ifconfig command to view the current device IP.

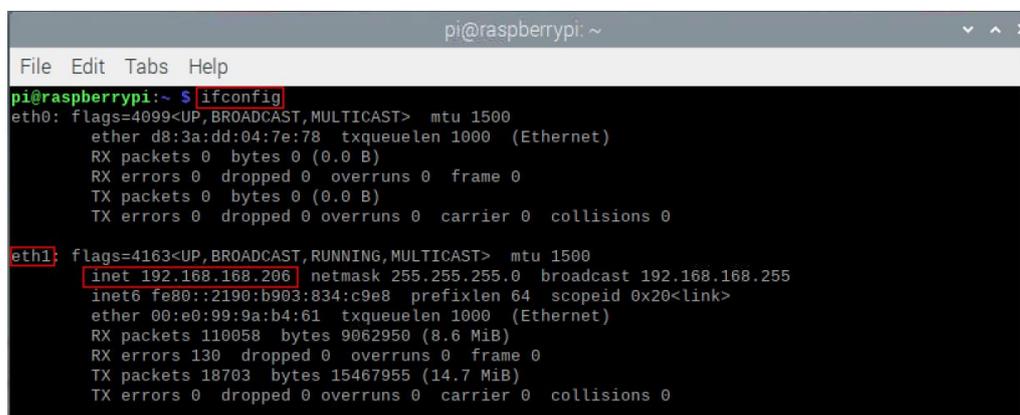
Preparation:

ED-IPC2600 device has been connected to the network through the router.

Steps:

Run the following command in the command pane to view the detailed information of each port of the device, where the inet value in the eth1 interface is the device IP, as shown in the following figure.

ifconfig



```

pi@raspberrypi: ~
File Edit Tabs Help
pi@raspberrypi:~$ ifconfig
eth0: flags=4099<UP,BROADCAST,MULTICAST> mtu 1500
    ether d8:3a:dd:04:7e:78 txqueuelen 1000 (Ethernet)
    RX packets 0 bytes 0 (0.0 B)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 0 bytes 0 (0.0 B)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0

eth1: flags=4163<UP,BROADCAST,RUNNING,MULTICAST> mtu 1500
    inet 192.168.168.206 netmask 255.255.255.0 broadcast 192.168.168.255
    inet6 fe80::2190:b903:834:c9e8 prefixlen 64 scopeid 0x20<link>
    ether 00:e0:99:9a:b4:61 txqueuelen 1000 (Ethernet)
    RX packets 110058 bytes 9062950 (8.6 MiB)
    RX errors 130 dropped 0 overruns 0 frame 0
    TX packets 18703 bytes 15467955 (14.7 MiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
  
```



NOTE:

If the two Ethernet ports of ED-IPC2600 are all connected to Ethernet, the two IP addresses found are all device IP addresses.

5.1.2 Login Router to Query IP

When the device starts normally but the display is not connected, you can log in to the router to check

the current device IP.

Preparation:

- ◆ ED-IPC2600 has been connected to the network through the router.
- ◆ The IP and network password of the router in the network have been obtained, and the IP address is 192.168.X.X.

Steps:

1. Open a browser, Enter the router IP of the network where ED-IPC2600 is located in the address bar: 192.168.x.x, and press Enter to enter the router login interface.
2. According to the interface prompts, enter the network password and enter the router management interface.
3. Find the IP address of ED-IPC2600 in the terminal device of the management interface.

5.1.3 Scan For Using NMAP Tool

When the device starts normally but the display is not connected, you can use Nmap tool to scan the IP under the current network to obtain the IP information of the device. Nmap supports Linux, macOS, Windows and other platforms.

Preparation:

- ◆ ED-IPC2600 has been connected to the network through the router.
- ◆ The IP segment and mask of the router in the network have been obtained, for example, 192.168.X.X/24, where 24 is the subnet mask.

Steps:

For example, using Nmap to scan the network segments from 192.168.3.0 to 255, you can use the following steps:

1. Open the Nmap tool and scan the hosts in the 192.168.X.X/24 network segment.

**NOTE:**

The Nmap tool operates differently in different operating systems, so please follow the actual interface or command prompts.

2. According to the scanned results, get the device IP of ED-IPC2600.

5.2 Remote Login

There are many remote login methods, and users can choose according to their actual needs. This chapter only introduces SSH and VNC.

5.2.1 Connect To The Device Via SSH

If the device uses Lite system, you can choose to connect to the device remotely through SSH to configure or debug it.

The tools for remote login are selected by users themselves, and the following is an example of logging in through MobaXterm.

Preparation:

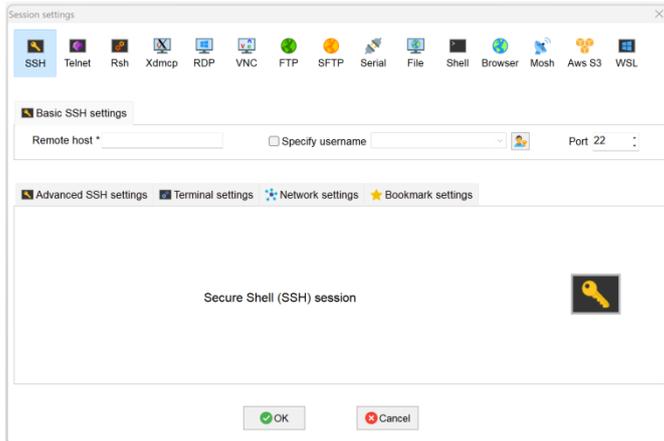
- ◆ The MobaXterm tool has been installed on the PC.
- ◆ ED-IPC2600 has been connected to the network through the router.
- ◆ IP address of ED-IPC2600 has been get.

Steps:

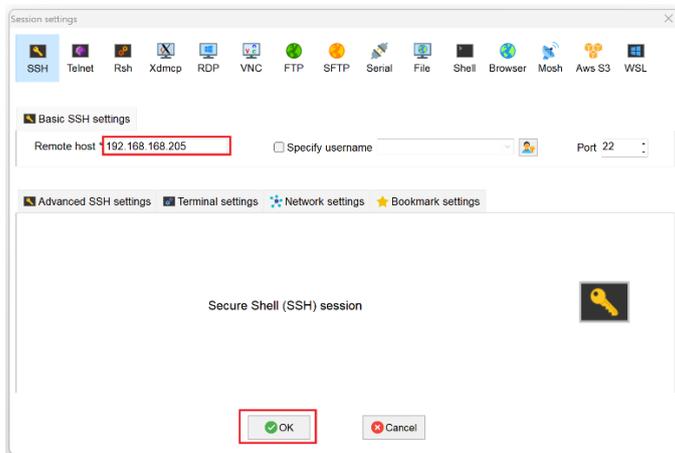
1. Open MobaXterm, click  ^{Session}, and open the window for creating connection, as shown in the figure below.



2. Click  ^{SSH} in the upper left corner to open the SSH connection interface.



3. After entering the IP address of the obtained ED-IPC2600, click "OK".



4. Click "Accept" in the pop-up prompt box to enter the system login interface.
5. Enter the username and password according to the prompt, and enter the system after logging in.



TIP:

Default username is pi, Default password is raspberry.

```
login as: pi
pi@192.168.168.205's password:

+ MobaXterm Personal Edition v23.0 +
+ (SSH client, X server and network tools)
+
+ SSH session to pi@192.168.168.205
+ Direct SSH : ✓
+ SSH compression : ✓
+ SSH-browser : ✓
+ X11-forwarding : ✓ (remote display is forwarded through SSH)
+
+ For more info, ctrl+click on help or visit our website.

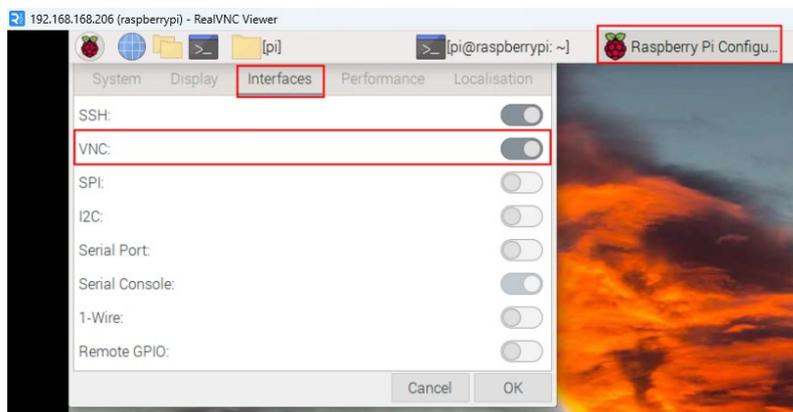
linux raspberrypi 5.10.92-v8+ #1514 SMP PREEMPT Mon Jan 17 17:39:38 GMT 2022 aarch64
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Sat May 6 10:07:19 2023 from 192.168.168.227
SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set a new password.
pi@raspberrypi:~$
```

5.2.2 Connect To The Device Desktop Through VNC

If the device uses Desktop system, you can choose to connect to the device remotely through VNC to configure or debug it.

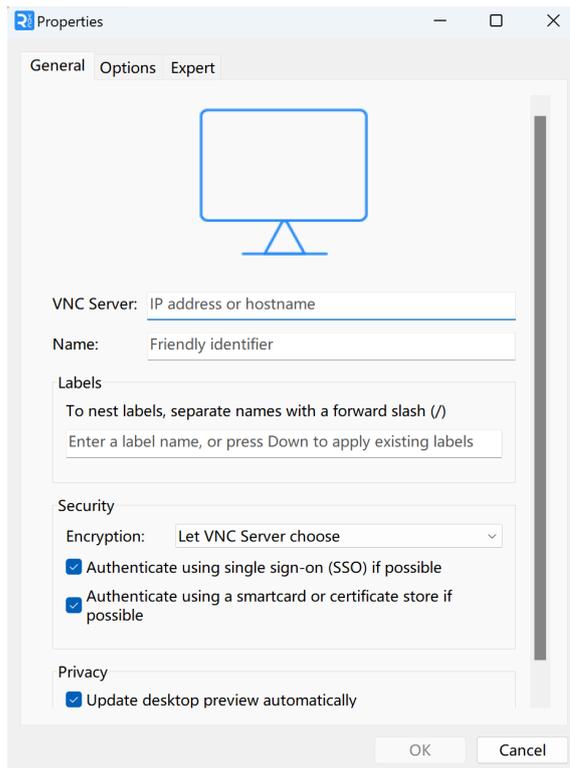
Preparation:

- ◆ The RealVNC Viewer tool has been installed on PC.
- ◆ ED-IPC2600 has been connected to the network through the router.
- ◆ IP address of ED-IPC2600 has been get.
- ◆ The VNC function in the ED-IPC2600 system has been turned on, as shown in the following figure.

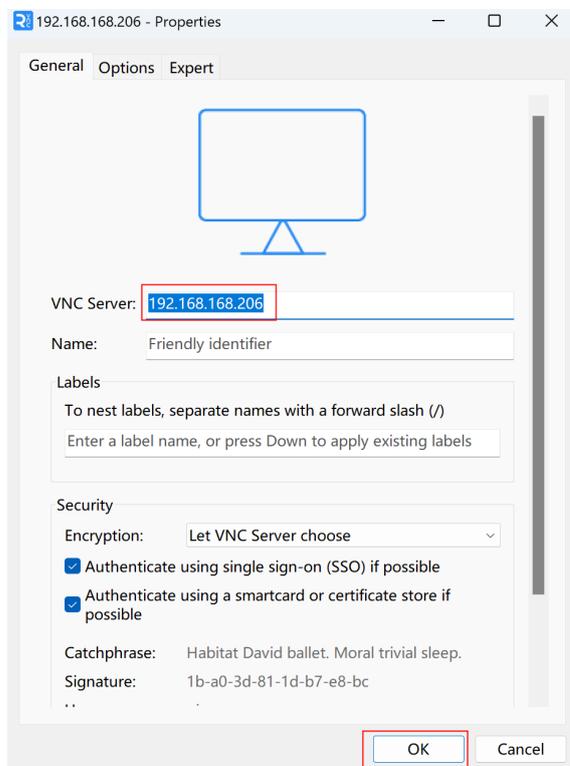


Steps:

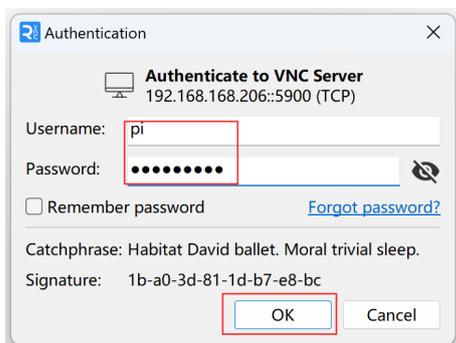
1. Open RealVNC Viewer and select "New connection..." in the File in the menu bar to open the window for creating a connection, as shown in the following figure.



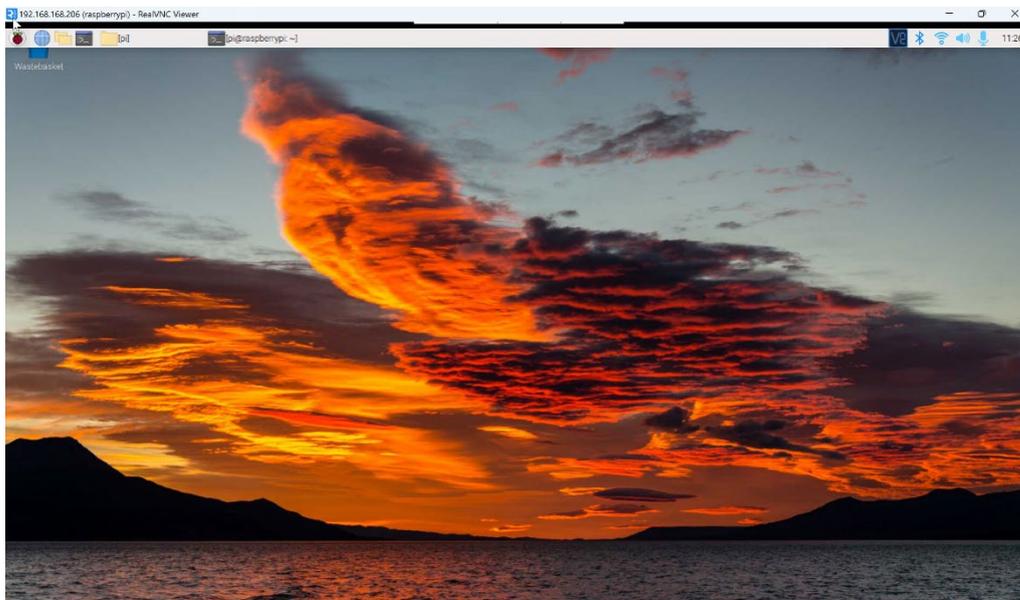
2. After entering the IP address of ED-IPC2600, click "OK".



3. Enter the username and password in the Authentication prompt box that pops up.

**TIP:****Default username is pi, Default password is raspberry.**

4. Select "OK" to log in and connect to the remote desktop.



5.3 Configuring Storage Devices

You can connect your external hard disk, SSD, SD card or USB stick to the corresponding port on the ED-IPC2600, and mount the file system to access the data stored on it. When the ED-IPC2600 device is turned off, it is necessary to unmount the storage device so that it can be safely pulled out.

The connectable storage devices of ED-IPC2600 include USB storage devices and SD cards. This chapter introduces how to configure the mounting and unmounting of storage devices.

5.3.1 Mounting a Storage Device

If the Lite version of the operating system is used (the Desktop version of the system supports automatic mounting), after the storage device is connected to the corresponding port on the ED-IPC2600, it is necessary to mount the storage device in a specific folder location through configuration, usually in the /mnt folder, such as /mnt/mydisk.



NOTE:

The "/mnt" folder must be empty.

Preparation:

The storage device is ready to be mounted.

Steps:

1. Connect the storage device to be mounted to the corresponding port on the ED-IPC2600 (USB storage device is inserted into USB port and SD card is inserted into SD card slot).
2. Run the following command to view all disk partitions on the ED-IPC2600.

```
sudo lsblk -o UUID,NAME,FSTYPE,SIZE,MOUNTPOINT,LABEL,MODEL
```

After running the command, the information displayed is as follows:

```
pi@raspberrypi:~ $ sudo lsblk -o UUID,NAME,FSTYPE,SIZE,MOUNTPOINT,LABEL,MODEL
UUID                                NAME      FSTYPE  SIZE MOUNTPOINT  LABEL  MODEL
7C9E-4F13                            sda              3.8G
                                sda1          vfat    3.8G /media/pi/ADMESY ADMESY
C336-AC83                            mmcblk0
                                mmcblk0p1    vfat    256M /boot          bootfs
eaaa4faa-eab6-400c-950f-dc96ae4e0400 mmcblk0p2    ext4     7G /              rootfs
                                mmcblk0boot0 4M
                                mmcblk0boot1 4M
```

- UUID、NAME、FSTYPE、SIZE、MOUNTPOINT、LABEL and MODEL are disk parameters

that need to be listed.

- The types of MOUNTPOINT are “/” and “/boot” .
 - The storage device whose LABEL is "ADMESY" is the inserted USB storage device, and the corresponding disk name is sda1.
 - FSTYPE indicates the file system type contained.
- ✓ If the file system type of the inserted storage device is exFAT, please run the following commands to install the exFAT driver.

sudo apt update

sudo apt install exfat-fuse

- ✓ If the file system type of the inserted storage device is NTFS (only read permission is supported), you can install ntfs-3g driver to realize write permission. Run the following commands to install ntfs-3g drivers.

sudo apt update

sudo apt install ntfs-3g

3. Run the following command to get the location of the disk partition.

sudo blkid

After running the command, the following information is displayed, which the disk partition of the connected storage device is displayed as "/dev/sda1".

```
pi@raspberrypi:~$ sudo blkid
/dev/mmcblk0p1: LABEL_FATBOOT="bootfs" LABEL="bootfs" UUID="C336-AC83" BLOCK_SIZE="512" TYPE="vfat"
PARTUUID="7902e585-01"
/dev/mmcblk0p2: LABEL="rootfs" UUID="eaaa4faa-eab6-400c-950f-dc96ae4e0400" BLOCK_SIZE="4096" TYPE="
ext4" PARTUUID="7902e585-02"
/dev/sda1: LABEL="ADMESY" UUID="7C9E-4F13" BLOCK_SIZE="512" TYPE="vfat"
```

4. Create a target folder as the mount point of the storage device. Assuming that the mount name is mydisk and the directory to be mounted is "/mnt", the command to be executed is as follows:

sudo mkdir /mnt/mydisk

5. Mount the storage device at the created mount point, and execute the following command:

sudo mount /dev/sda1 /mnt/mydisk

6. Verify the success of mounting the storage device by executing the following command.

ls /mnt/mydisk

- ✓ After executing the command, if the displayed information lists all files in the storage device, it means that the mount is successful.
- ✓ After executing the command, if the displayed information does not list the contents of related files, it means that the mount is failed.

5.3.2 Unmount The Storage Device

When the ED-IPC2600 device is turned off, it is necessary to manually unmount the storage device so that it can be pulled out safely.



Both Lite and Desktop versions of the system need to manually unmount the storage device.

Preparation:

The storage device has been successfully mounted.

Steps:

If "/mnt" is the mounted directory and "mydisk" is the name of the mount point, you can execute the following command to complete the unmounting.

sudo umount /mnt/mydisk

- ✓ After executing the command, if no error message is displayed, it means that the unmounting has been completed and the storage device can be completely pulled out.
- ✓ After executing the command, if an error message is displayed, it means that the unmounting is failed.

5.3.3 Set The Storage Device To Mount Automatically

If you are using the Lite version of operating system, you can automatically mount it by modifying the fstab settings.

Preparation:

The storage device to be mounted has been connected to the corresponding port on the ED-IPC2600 device.

Steps:

1. Execute the following command to view all disk partitions on the ED-IPC2600 and get the file system type of the storage device to be mounted, as "vfat" shown in the figure below.

sudo lsblk -o UUID,NAME,FSTYPE,SIZE,MOUNTPOINT,LABEL,MODEL

```
pi@raspberrypi:~$ sudo lsblk -o UUID,NAME,FSTYPE,SIZE,MOUNTPOINT,LABEL,MODEL
UUID                                NAME      FSTYPE  SIZE MOUNTPOINT  LABEL  MODEL
7C9E-4F13                            sda       vfat    3.8G /media/pi/ADMESY ADMESY  Flash_Disk
C336-AC83                            mmcblk0
| -mmcblk0p1                         vfat     256M  /boot        bootfs
eaaa4faa-eab6-400c-950f-dc96ae4e0400 -mmcblk0p2 ext4      7G    /            rootfs
mmcblk0boot0                         4M
mmcblk0boot1                         4M
```

2. Execute the following command to obtain the UUID of the storage device to be mounted, such as "7C9E-4F13" in the figure below.

sudo blkid

```
pi@raspberrypi:~$ sudo blkid
/dev/mmcblk0p1: LABEL_FATBOOT="bootfs" LABEL="bootfs" UUID="C336-AC83" BLOCK_SIZE="512" TYPE="vfat"
PARTUUID="7902e585-01"
/dev/mmcblk0p2: LABEL="rootfs" UUID="eaaa4faa-eab6-400c-950f-dc96ae4e0400" BLOCK_SIZE="4096" TYPE="
ext4" PARTUUID="7902e585-02"
/dev/sda1: LABEL="ADMESY" UUID="7C9E-4F13" BLOCK_SIZE="512" TYPE="vfat"
```

3. Execute the following command to open the fstab file.

sudo nano /etc/fstab

4. Add the following to the fstab file.

```
UUID=7C9E-4F13 /mnt/mydisk vfat defaults,auto,users,rw,nofail 0 0
```

- ✓ The value of UUID is the value found in Step 2 above.
- ✓ "/mnt" is the directory to be mounted, and mydisk is the name of the mount point.
- ✓ Vfat is the file system type queried in step 1.
- ✓ If the type of file system is FAT or NTFS, the added content is "UUID = 7C9E-4F13 /mnt/mydisk vfat defaults,auto,users,rw,no fail umask = 000 0 0", which will allow all users to "read/write" access to each file on the storage device.



NOTE:

More information about the **fstab** command can be viewed by executing the **man fstab** command.

5. Use Ctrl+X to save the file and exit edit mode.

5.4 Configuring Ethernet IP

The IP address is automatically obtained by default. If you need to reconfigure the IP, you can configure it through NetworkManager and dhcpcd.

5.4.1 Configure IP by Using The NetworkManager Tool

The operating systems of Desktop and Lite have enabled NetworkManager by default, which can be directly configured by using NetworkManager.

5.4.1.1 Raspberry Pi OS(Desktop)

In the Desktop version of the operating system, it is recommended to use the graphical NetworkManager tool to configure IP.



NOTE:

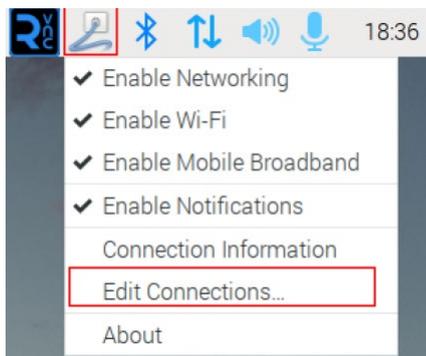
The Desktop version of the operating system has the NetworkManager graphical tool installed by default.

Preparation:

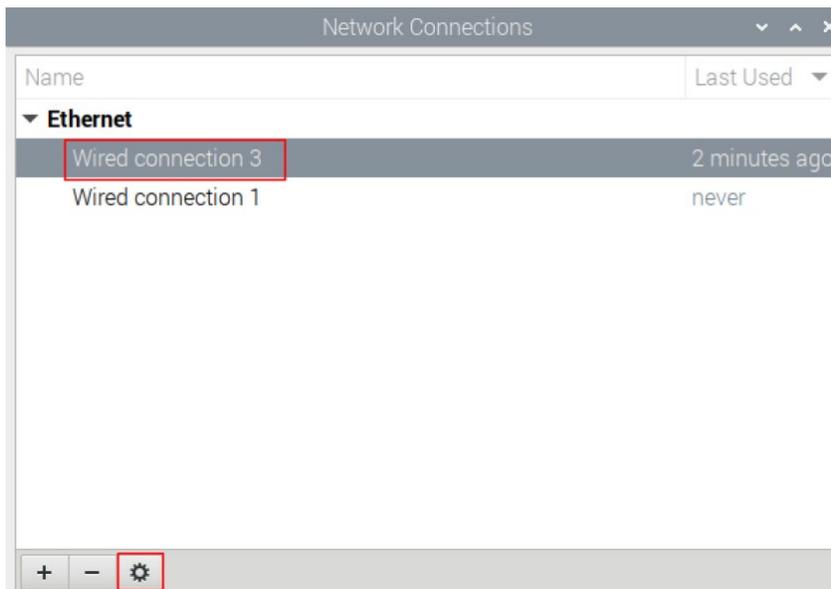
NetworkManager is enabled.

Steps:

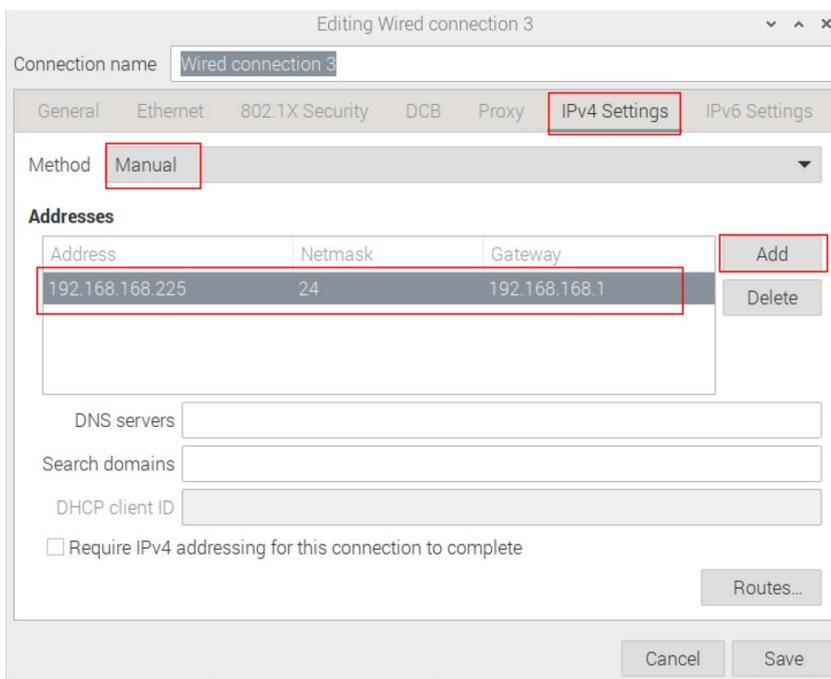
1. Right-click the NetworkManager icon  and select "Edit Connections..." from the menu.



2. In the pop-up "Network Connections" pane, select the connection name to be modified, and then click the Settings button below.



3. In the pop-up "Editing Wired connection" pane, select the "IPv4 Settings" page, and then set the IP address as required.
 - If you want to set the IP as a static IP, set the "Method" as "Manual", add an entry in Addresses and enter the corresponding IP address information.



- If you want to set the IP to automatic acquisition mode, you only need to set the "Method" as "Automatic(DHCP)".

4. Click "save" to return to "Network Connections" pane and close the page.
5. Execute the **sudo reboot** command to restart the device.

5.4.1.2 Raspberry Pi OS(Lite)

In the Lite version of operating system, it is recommended to use the command to configure IP.

Preparation:

NetworkManager is enabled.

Steps:

Set a static IP address

1. Get the assigned IP address, subnet mask and gateway address, for example, the IP address is 192.168.1.101/24 and the gateway IP is 192.168.1.1.
2. Open the command terminal pane and execute the following command to set the IP address to the obtained IP address.

```
sudo nmcli connection modify <name> ipv4.addresses 192.168.1.101/24 ipv4.method manual
```

3. Execute the following command to set the gateway IP to the obtained gateway IP.

```
sudo nmcli connection modify <name> ipv4.gateway 192.168.1.1
```

Set the IP to automatic mode

Execute the following command to set the way of obtaining IP address to automatic mode.

```
sudo nmcli connection modify <name> ipv4.method auto
```

5.4.2 Configure IP by Using The dhcpd Tool

Since NetworkManager is enabled on the Desktop and Lite of operating systems by default. If you need to switch to using the dhcpd tool for configuration, you need to stop and disable the NetworkManager service and enable the dhcpd service before configuration.

Steps:

1. Execute the following command to stop the NetworkManager service.

```
sudo systemctl stop NetworkManager
```

2. Execute the following command to disable the NetworkManager service.

```
sudo systemctl disable NetworkManager
```

3. Execute the following command to enable the dhcpd service.

```
sudo systemctl enable dhcpd
```

4. Execute the following command to restart the device.

```
sudo reboot
```

5. Execute the following command to open the /etc/dhcpd.conf file.

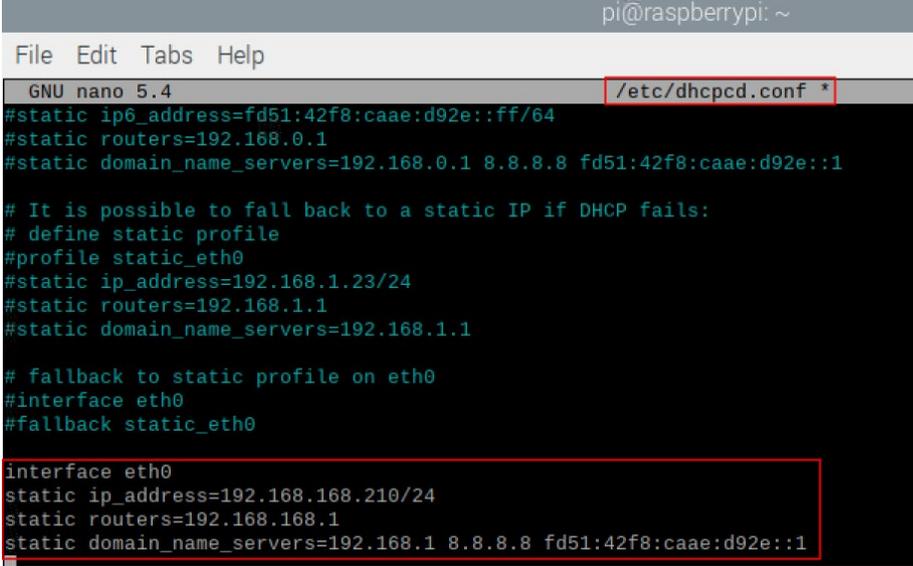
```
sudo nano /etc/dhcpd.conf
```

6. Add the following content at the end of the /etc/dhcpd.conf file.

```
interface eth0  
static ip_address=192.168.168.210/24  
static routers=192.168.168.1  
static domain_name_servers=192.168.168.1 8.8.8.8 fd51:42f8:caae:d92e::1
```

- ✓ *eth0* is the Ethernet port of the IP to be configured;
- ✓ 192.168.0.10/24 indicates the IP address and subnet mask to be configured;

- ✓ 192.168.0.1 indicates the gateway IP to be configured;
- ✓ 8.8.8.8 represents the DNS server address, which should be configured according to the actual needs.
- ✓ fd51:42f8:caae:d92e::1 indicates the IPV6 address, which should be configured according to the actual needs.



```
pi@raspberrypi: ~
File Edit Tabs Help
GNU nano 5.4 /etc/dhcpd.conf *
#static ip6_address=fd51:42f8:caae:d92e::ff/64
#static routers=192.168.0.1
#static domain_name_servers=192.168.0.1 8.8.8.8 fd51:42f8:caae:d92e::1

# It is possible to fall back to a static IP if DHCP fails:
# define static profile
#profile static_eth0
#static ip_address=192.168.1.23/24
#static routers=192.168.1.1
#static domain_name_servers=192.168.1.1

# fallback to static profile on eth0
#interface eth0
#fallback static_eth0

interface eth0
static ip_address=192.168.168.210/24
static routers=192.168.168.1
static domain_name_servers=192.168.1 8.8.8.8 fd51:42f8:caae:d92e::1
```

7. Use Ctrl+X to save the file and exit edit mode.

5.5 Configuring Wi-Fi (Optional)

User can choose the ED-IPC2600 with Wi-Fi version, which needs to be configured before using Wi-Fi function.

5.5.1 Enable Wi-Fi Function

The Wi-Fi function is blocked by default, and you need to set the country region to enable it.

5.5.1.1 Raspberry Pi OS(Desktop)

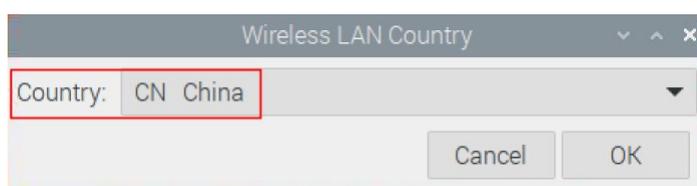
In the Desktop version of the operating system, you can use the desktop icon to open the configuration window for setting.

Steps:

1. Left-click the icon  in the upper right corner of the desktop and select "Click here to set Wi-Fi country" from the menu.



2. Set the value of Country in the pop-up "Wireless LAN Country" pane, and select it according to the actual region.



3. Select "OK" to complete the setting.

5.5.1.2 Raspberry Pi OS(Lite)

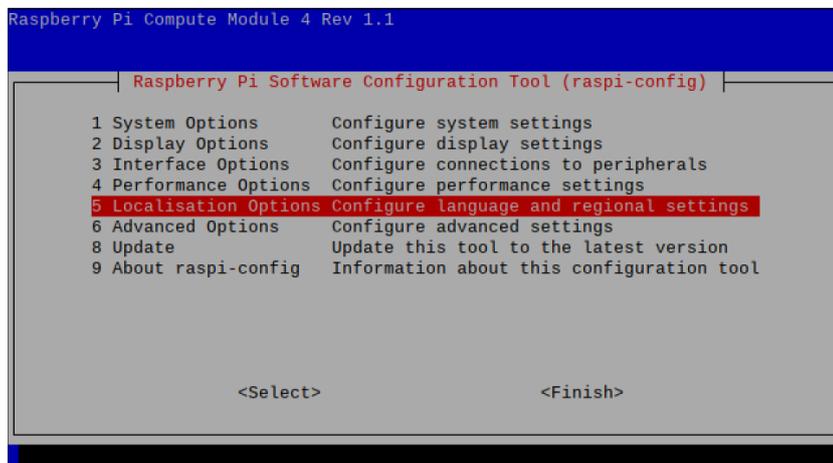
In the Lite version of the operating system, WiFi can be enabled through the command line.

Setps:

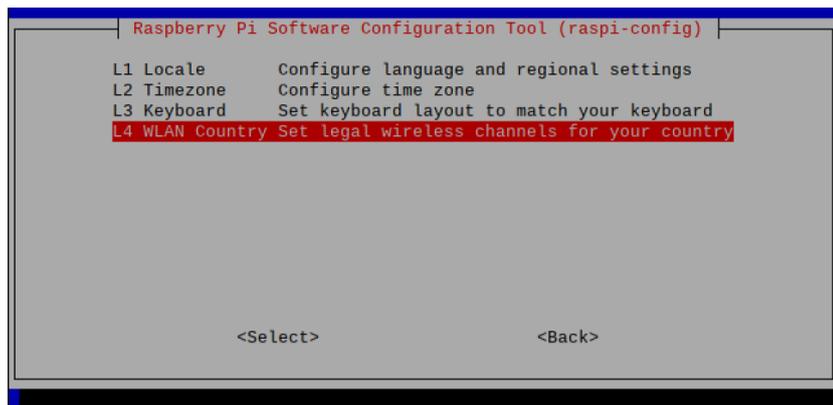
1. Open the command terminal pane and execute the following command to open the Raspberry Pi Software Configuration Tool (raspi-config) interface.

sudo raspi-config

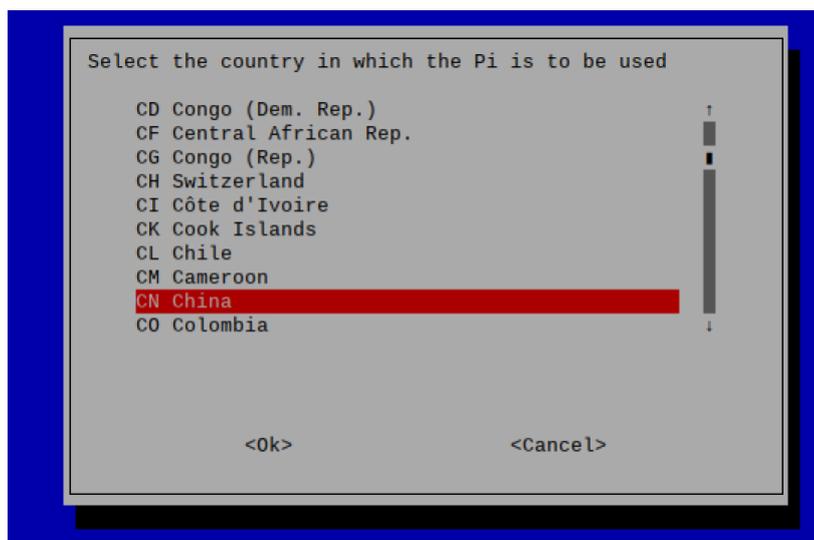
2. Choose "5 Localisation Options" and press Enter.



3. Select "L4 WLAN Country" and press Enter.



4. Select a country code according to the actual region and press Enter.



5. Open "Wireless LAN country set to CN" interface.



6. Press Enter to exit the main interface of the pane, select "Finish" and press Enter to complete the setting and return to the command line.

5.5.2 Use The NetworkManager Tool To Configure WiFi Connections

The operating systems of Desktop and Lite have enabled NetworkManager by default, which can be directly configured by using NetworkManager.

5.5.2.1 Raspberry Pi OS(Desktop)

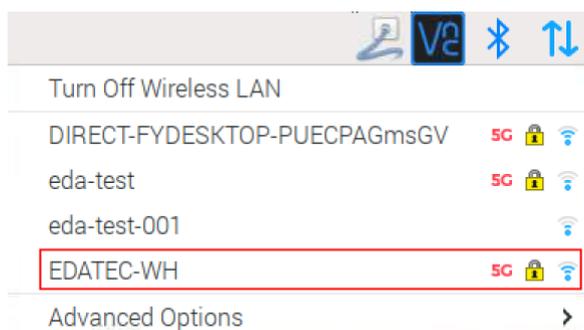
In the Desktop version of the operating system, you can connect to WiFi through the desktop icon.

Preparation:

WiFi function is enabled.

Steps:

1. Left-click the  icon in the upper right corner of the desktop, select the WiFi to be connected in the pop-up WiFi list and click.



2. Enter the WiFi Password in the pop-up "Wi-Fi Network Authentication Required" pane.



3. Click "Connect" to connect to the network. After the connection is completed, the WiFi icon will be displayed normally in the upper right corner of the desktop.

5.5.2.2 Raspberry Pi OS(Lite)

In the Lite version of the operating system, it is supported to configure WiFi through the command line.

Preparation:

- WiFi function is enabled.
- The WiFi name and password that can be connected are prepared, for example, the WiFi name is SSID and the password is password.

Steps:

1. Open the terminal and execute the following command to scan the list of connectable WiFi name.

sudo nmcli device wifi

```

pi@raspberrypi:~$ sudo nmcli device wifi
IN-USE BSSID SSID MODE CHAN RATE
C2:82:9B:0A:F9:51 EDATEC-WH Infra 44 270 Mbit/s
D2:0F:0C:C8:83:49 DIRECT-FYDESKTOP-PUECPAGmsGV Infra 36 270 Mbit/s
C2:82:9B:0A:F9:4D EDATEC-WH Infra 6 130 Mbit/s
58:41:20:8B:16:B2 eda-test Infra 1 405 Mbit/s
5A:41:20:AB:16:B2 -- Infra 1 405 Mbit/s
5A:41:20:9B:16:B2 eda-test-001 Infra 1 405 Mbit/s
58:41:20:8B:16:B4 eda-test Infra 157 405 Mbit/s
5A:41:20:DB:16:B2 -- Infra 157 405 Mbit/s

```

2. Execute the following command to connect the WiFi to be accessed.

sudo nmcli device wifi connect SSID password password

Where SSID is the name of the WiFi to be connected and password is the password of the WiFi to be connected.

- Execute the following command to set up automatic WiFi connection.

```
sudo nmcli connection modify SSID connection.autoconnect yes
```

Where SSID is the name of the WiFi to be connected.

5.5.3 Configure WiFi Connection By Using dhcpcd Tool

In both Desktop and Lite versions of the operating system, you can connect to WiFi through the dhcpcd tool.

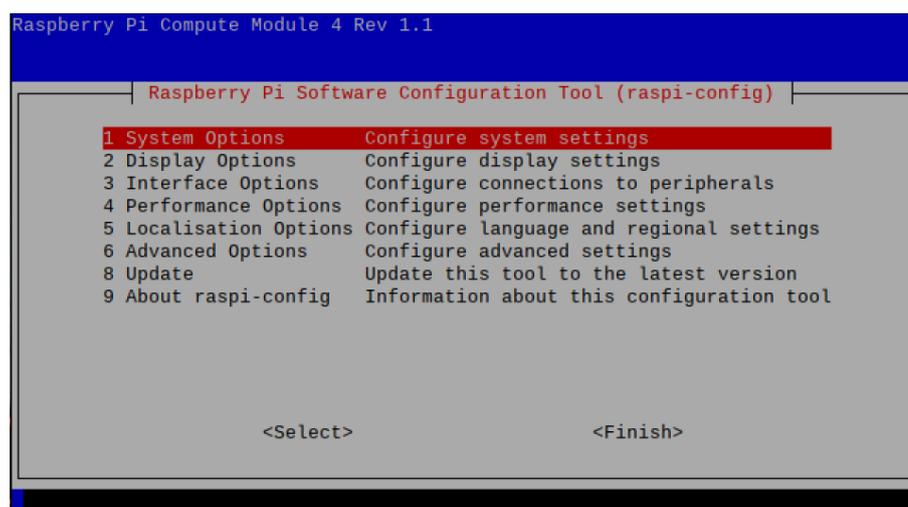
Preparation:

- WiFi function is enabled.
- The WiFi name and password that can be connected are prepared, for example, the WiFi name is EDATEC-WH and the password is password.

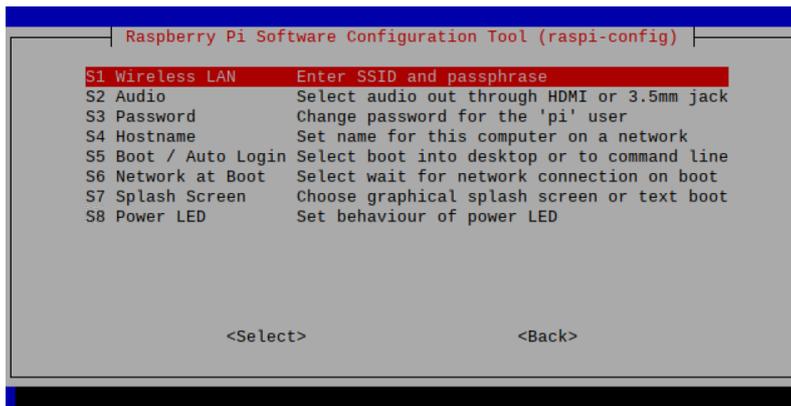
Steps:

- Open the terminal and execute the following command to open the Raspberry Pi Software Configuration Tool (raspi-config) interface.

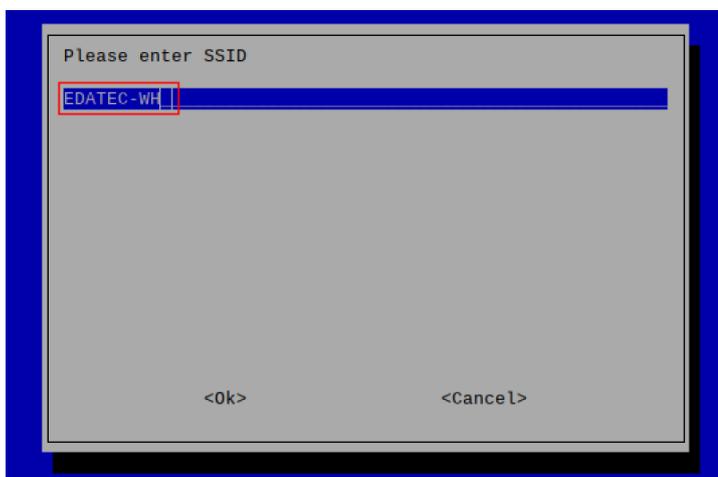
```
sudo raspi-config
```



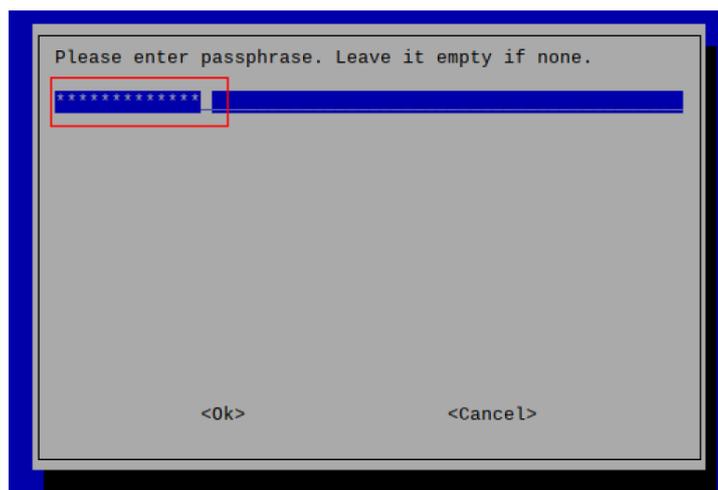
- Select "1 System Options" and press Enter, and then select "S1 Wireless LAN" in the interface.



3. Press Enter and enter the WiFi name in the "Please enter SSID" interface.



4. Press Enter to enter the WiFi password in the "Please enter passphrase. Leave it empty if none" interface.



5. Press Enter to exit the main interface of the pane, select "Finish" and press Enter to complete the setting and return to the command line window.

5.6 Configuring Bluetooth (optional)

User can choose ED-IPC2600 with Bluetooth version, and the Bluetooth function is enabled by default, so relevant configuration is required before using Bluetooth.

5.6.1 Basic Configuration Command

Command	Function Description
<code>bluetoothctl scan on</code>	Enable Bluetooth scanning
<code>bluetoothctl scan off</code>	Disable Bluetooth scanning
<code>bluetoothctl discoverable on</code>	Enable Bluetooth discovery (which can be discovered by the other party)
<code>bluetoothctl discoverable off</code>	Disable Bluetooth discovery
<code>bluetoothctl trust <i>device_MAC</i></code>	Trust device
<code>bluetoothctl connect <i>device_MAC</i></code>	Connect device
<code>bluetoothctl disconnect <i>device_MAC</i></code>	Disconnect device

5.6.2 Configuration Example

This chapter introduces how to configure Bluetooth through a configuration example.

Preparation:

- Bluetooth scanning is enabled.
- Bluetooth discovery is enabled.

Steps:

1. Enter the Bluetooth view;

```
sudo bluetoothctl
```

2. Enable bluetooth.

```
power on
```

3. Scan Bluetooth device.

```
scan on
```

Returned display information:

```
Discovery started
```

```
[CHG] Controller B8:27:EB:85:04:8B Discovering: yes
[NEW] Device 4A:39:CF:30:B3:11 4A-39-CF-30-B3-11
```

4. Find the name of the turned-on Bluetooth device;

devices

Returned display information:

```
Device 6A:7F:60:69:8B:79 6A-7F-60-69-8B-79
Device 67:64:5A:A3:2C:A2 67-64-5A-A3-2C-A2
Device 56:6A:59:B0:1C:D1 Lefun
Device 34:12:F9:91:FF:68 test
```

5. Pairing target devices;

```
pair 34:12:F9:91:FF:68
```

```
34:12:F9:91:FF:68 is target device's device_MAC
```

Returned display information:

```
Attempting to pair with 34:12:F9:91:FF:68
[CHG] Device 34:12:F9:91:FF:68 ServicesResolved: yes
[CHG] Device 34:12:F9:91:FF:68 Paired: yes
Pairing successful
```

6. Add as trusted device

```
trust 34:12:F9:91:FF:68
```

```
34:12:F9:91:FF:68 is target device's device_MAC
```

Returned display information:

```
[CHG] Device 34:12:F9:91:FF:68 Trusted: yes
Changing 34:12:F9:91:FF:68 trust succeeded
```

5.7 Configuring 4G (Optional)

User can choose ED-IPC2600 with 4G version, which needs to be configured before using 4G network.

5.7.1 Use The NetworkManager Tool To Configure The Network

If you need to connect to a 4G network, you need to create a gsm network connection first. The following configuration is based on different scenarios.

5.7.1.1 Scenarios Without APN Configuration

If the user's 4G network does not need to be configured with APN, it can be configured according to the following steps.

Steps:

1. Customize a gsm network name, such as 4G1.
2. Execute the following command to create a gsm network named 4G-1.

```
sudo nmcli connection add type gsm con-name 4G1
```

```
pi@raspberrypi:~ $ sudo nmcli connection add type gsm con-name 4G1  
Connection '4G1' (cbf903af-bd5f-4039-a24c-d423c641558c) successfully added.
```

5.7.1.2 Scenarios With APN Configuration

If the user's 4G network needs to be configured with APN, it can be configured with reference to the following steps.

Steps:

1. Customize a gsm network name (for example, 4G2) and get the name of APN (for example, apn1).
2. Execute the following command to create a gsm network named 4G2.

```
sudo nmcli connection add type gsm con-name 4G2 ifname cdc-wdm0 gsm.apn apn1
```

```
pi@raspberrypi:~ $ sudo nmcli connection add type gsm con-name 4G2 ifname cdc-wd  
m0 gsm.apn apn1  
Connection '4G2' (df62b252-7db8-4547-adb0-f5456590bc76) successfully added.
```

5.7.1.3 Scenario Where Username And Password Need To Be Configured

If the user's 4G network needs to be configured with a username and password, you can refer to the following steps.

Steps:

1. Customize a gsm network name (for example, 4G3), and respectively obtain the number, name and password of the gsm network to be configured (for example, 777, mycdma, mobile).
2. Execute the following command to create a gsm network named 4G3.

```
sudo nmcli connection add type gsm con-name 4G3 ifname cdc-wdm0 ifname cdc-wdm0  
gsm.number 777 gsm.username mycdma gsm.password mobile
```

```
pi@raspberrypi:~$ sudo nmcli connection add type gsm con-name 4G3 ifname cdc-wd  
m0 ifname cdc-wdm0 gsm.number 777 gsm.username mycdma gsm.password mobile  
Connection '4G3' (e097bf5a-f44f-40ca-814e-4c66de9941ec) successfully added.
```

5.7.2 Configure The Network By Using The dhcpd Tool

By default, automatic dialing is prohibited in 4G networks. If users want to start automatic dialing and use the network, they need to enable "lte-reconnect.service" service. Configure as follows according to different scenarios requirements.

5.7.2.1 Scenarios Without APN Configuration

If the user's 4G network does not need to be configured with APN, it can be configured according to the following steps.

Steps:

1. Execute the following command to enable the "lte-reconnect.service" service.

```
sudo systemctl enable lte-reconnect.service
```

2. Execute the following command to start the "lte-reconnect.service" service and make automatic dialing.

```
sudo systemctl start lte-reconnect.service
```

3. Execute the following command to check the status of the wwan interface.

ifconfig

5.7.2.2 Scenarios With APN Configuration

If the user's 4G network needs to be configured with APN, it can be configured with reference to the following steps.

Steps:

1. Get the name of APN (for example, APN22).
2. Execute the following command to enable the "lte-reconnect.service" service.

```
sudo systemctl enable lte-reconnect.service
```

3. Execute the following command to start the "lte-reconnect.service" service and make automatic dialing.

```
sudo systemctl start lte-reconnect.service
```

4. Execute the following command to check the status of the wwan interface.

ifconfig

5. Execute the following command to open /usr/share/ed-ec20-qmi/lte-reconnect.sh file.

```
sudo nano /usr/share/ed-ec20-qmi/lte-reconnect.sh
```

6. Change the dialing command "\$BSP_HOME_PATH/quectel-CM -4 -f \$LOGFILE &" to "\$BSP_HOME_PATH/quectel-CM -4 -f \$LOGFILE -s apn22 &". Where "apn22" is the name of the obtained APN.
7. Use Ctrl+X to save the file and exit edit mode.
8. Execute the following command to restart the "lte-reconnect.service" service.

```
sudo systemctl restart lte-reconnect.service
```

5.7.3 Configure 4G Module Reset

When the device fails to recognize the SIM card, you can reset the 4G module through the command line.

Steps:

1. Execute the following commands to detect and install gpiod tools.

sudo apt update

sudo apt install gpiod

2. Execute the following command to reset the 4G module.

gpioset -m time -s 1 3 3=0

Where the first 3 indicates gpiochip and the second 3 indicates that the controlled gpio pin is GPIO3.

5.8 Configuring Buzzer

The ED-IPC2600 contains a buzzer, which supports manually configure the buzzer to turn on and off.

1. Execute the following commands to detect and install gpiod tools.

```
sudo apt update
```

```
sudo apt install gpiod
```

2. Execute the following commands to check the number of gpiochip.

```
gpiodetect
```

In the result, the gpiochip of [10-0020] (16 lines) is the gpiochip of the buzzer.

3. Execute the following command to turn on and turn off the buzzer.

- ◆ Turn on the buzzer:

```
gpioset 3 2=1
```

- ✓ 3 indicates the number of gpiochip queried in step 2.

- ✓ 2 indicates that the controlled gpio pin is GPIO2.

- ✓ 1 indicates the high level.

- ◆ Turn off the buzzer:

```
gpioset 3 2=0
```

- ✓ 3 indicates the number of gpiochip queried in step 2.

- ✓ 2 indicates that the controlled gpio pin is GPIO2.

- ✓ 0 indicates the low level.

5.9 Configuring RTC

ED-IPC2600 contains an integrated RTC, which automatically reads the system time synchronously by default, and can manually read and write the system time into RTC.

- ◆ Execute the following command to read the RTC time manually.

```
sudo hwclock -r
```

- ◆ Execute the following command to write the system time into RTC.

```
sudo hwclock -w
```

5.10 Configuring Serial Port

This chapter introduces the configuration method of RS232 and RS485.

5.10.1 Install picocom tool

In the Linux environment, you can use the picocom tool to debug the serial ports RS232 and RS485.

Execute the following command to install the picocom tool.

```
sudo apt-get install picocom
```

5.10.2 Configure RS232

ED-IPC2600 includes 2 RS232 ports, and the corresponding COM ports and device files are as follows:

Number of RS232 Ports	Corresponding COM Port	Corresponding Device File
2	COM1, COM3	/dev/com1, /dev/com3

Preparation:

The RS232 port of ED-IPC2600 has been connected with external device.

Steps:

1. Execute the following command to open the serial port com1, and configure the serial port baud rate to 115200.

```
picocom -b 115200 /dev/com1
```

2. Input commands as needed to control external device.

5.10.3 Configure RS485

ED-IPC2600 includes 2 RS485 ports, and the corresponding COM ports and device files are as follows:

Number of RS485 Ports	Corresponding COM Port	Corresponding Device File
2	COM2, COM4	/dev/com2, /dev/com4

Preparation:

The RS485 port of ED-IPC2600 has been connected with external devices.

Steps:

1. Execute the following command to open the serial port com4, and configure the serial port baud rate to 115200.

```
picocom -b 115200 /dev/com4
```

2. Input commands as needed to control external devices.

5.11 Configuring DO Port

ED-IPC2600 contains 4 or 8 DI ports, user can configure these ports according to actual needs.

Model	Number of ports	DO ports	Corresponding extended GPIO
ED-IPC2610	8	Y0	GPIO8
		Y1	GPIO9
		Y2	GPIO10
		Y3	GPIO11
ED-IPC2630		Y4	GPIO12
		Y5	GPIO13
		Y6	GPIO14
		Y7	GPIO15
ED-IPC2620	4	Y0	GPIO8
		Y2	GPIO10
		Y4	GPIO12
		Y6	GPIO14

Preparation:

The connection between the DO port of ED-IPC2600 and the external load has been completed.

Steps:

1. Execute the following commands to detect and install gpiod tools.

```
sudo apt update
```

```
sudo apt install gpiod
```

2. Execute the following commands to check the number of gpiochip.

```
gpiodetect
```

In the result, the gpiochip of [1-0027] (16 lines) is the gpiochip of the DO.

3. Execute the following command to set the output to high level or low level

- ◆ Setting the output to high level

```
gpiowrite 2 10=1
```

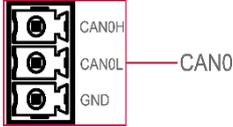
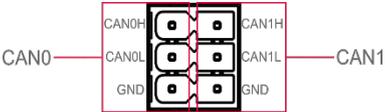
- ✓ 2 indicates the number of gpiochip.
- ✓ 10 indicates that the controlled gpio pin is GPIO10(Y2).
- ✓ 1 indicates the high level.
- ◆ Setting the output to low level

gpioset 2 10=0

- ✓ 2 indicates the number of gpiochip.
- ✓ 10 indicates that the controlled gpio pin is GPIO10(Y2).
- ✓ 1 indicates the high level.

5.12 Configuring CAN Port

ED-IPC2600 contains up to 2 CAN ports. Different models corresponding to different number of CAN ports, as shown in the following table:

Model	Number of ports	Correspondence between panel silkscreen and ports
ED-IPC2620	1	
ED-IPC2630	2	

5.12.1 Install can-utils tool

Execute the following commands to detect and install can-utils tools.

```
sudo apt update
```

```
sudo apt install can-utils
```

5.12.2 Set CAN port status

Preparation:

The connection between the CAN port of ED-IPC2600 and the external device has been completed.

Steps:

1. Execute the following commands to set the baud rate of CAN port to 1000000.

```
sudo ip link set can0 type can bitrate 1000000
```

Where can0 is the port number, and the value includes can0 and can1.

2. Execute the following commands to open CAN port.

sudo ip link set *can0* up

Where *can0* is the port number, and the value includes *can0* and *can1*.

3. Execute the following commands to set the communication of CAN port.

- Receiving Data

candump *can0*

- Sending Data

cansend *can0* 123#1122334455667788

Where *can0* is the port number, and the value includes *can0* and *can1*.

123#1122334455667788 is the information to be sent, and the user can customize it according to the format.

5.13 Configuring USER Indicator

ED-IPC2600 contains a USER indicator, and users can customize the status according to actual needs.

1. Execute the following commands to detect and install gpiod tools.

sudo apt update

sudo apt install gpiod

2. Execute the following command to turn on and turn off the USER indicator.

- ◆ Turn on the USER indicator:

gpioset -m time -s 1 3 5=0

- ✓ 3 indicates the number of gpiochip.
- ✓ 5 indicates that the controlled gpio pin is GPIO5.
- ✓ 0 indicates the high level.

- ◆ Turn off the USER indicator:

gpioset -m time -s 1 3 5=1

- ✓ 3 indicates the number of gpiochip.
- ✓ 5 indicates that the controlled gpio pin is GPIO5.
- ✓ The last 1 indicates the low level.