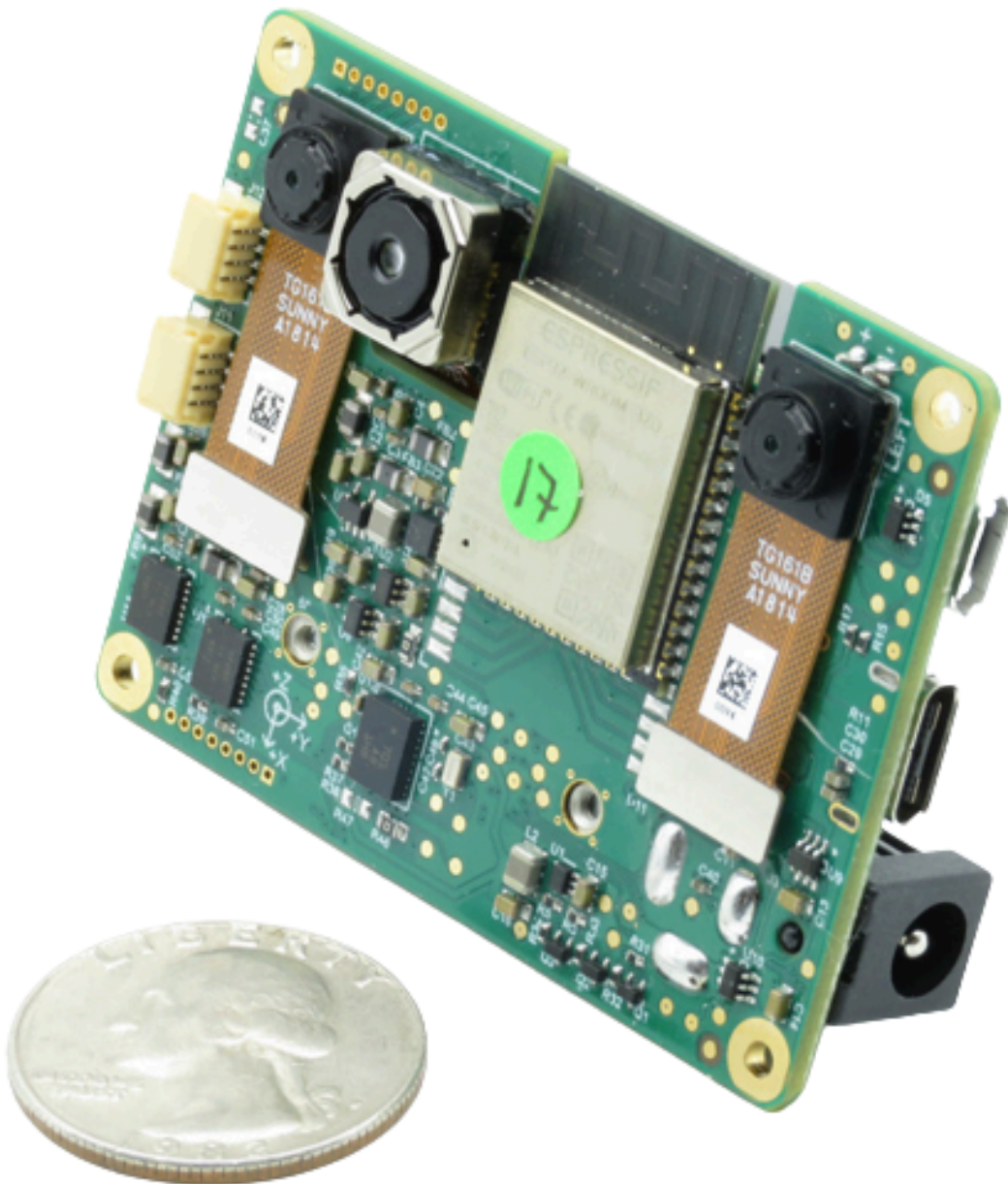


# OAK-D-IOT-40

## ⚠ Warning

OAK IoT series is now **community supported only**, and is **provided as-is**. This means we most likely **won't update it** and **we don't provide support** for it (Discord, forums, email...).

[Buy it on Luxonis shop](#)



## Overview

The **OAK-D-IoT-40** baseboard has three on-board cameras which implement stereo and RGB vision, piped directly into the [OAK-SoM-IoT](#) for depth and AI processing. The data can be then output to a host via USB 3.1 Gen1 (Type-C) or via ESP32 WiFi interface. If you are **new to OAK IOT devices**, you can check [Getting started with OAK IoT devices](#) tutorial.

This design is one of two baseboards for the [OAK-SoM-IoT](#), the other one being [OAK-D-IOT-75](#). The only difference is the stereo baseline distance and the shape/size of the OAK camera.

## Hardware specifications

This OAK camera uses USB-C cable for communication and power. It supports both USB2 and USB3 (5Gbps / 10Gbps).

## Camera module specifications

You can select either Fixed Focus (FF) or Auto Focus (AF) color camera, more [information here](#).

Camera Specs	Color camera	Stereo pair
Sensor	IMX378 (PY004 AF, PY052 FF)	OV9282 (PY003)
DFOV / HFOV / VFOV	81° / 69° / 55°	89° / 80° / 55°
Resolution	12MP (4056x3040)	1MP (1280x800)
Focus	AF: 8cm - ∞ or FF: 50cm - ∞	FF: 19.6cm - ∞
Max Framerate	60 FPS	120 FPS
F-number	1.8 ±5%	2.0 ±5%
Lens size	1/2.3 inch	1/4 inch
Effective Focal Length	4.81mm	2.35mm
Pixel size	1.55µm x 1.55µm	3µm x 3µm

## RVC2 inside

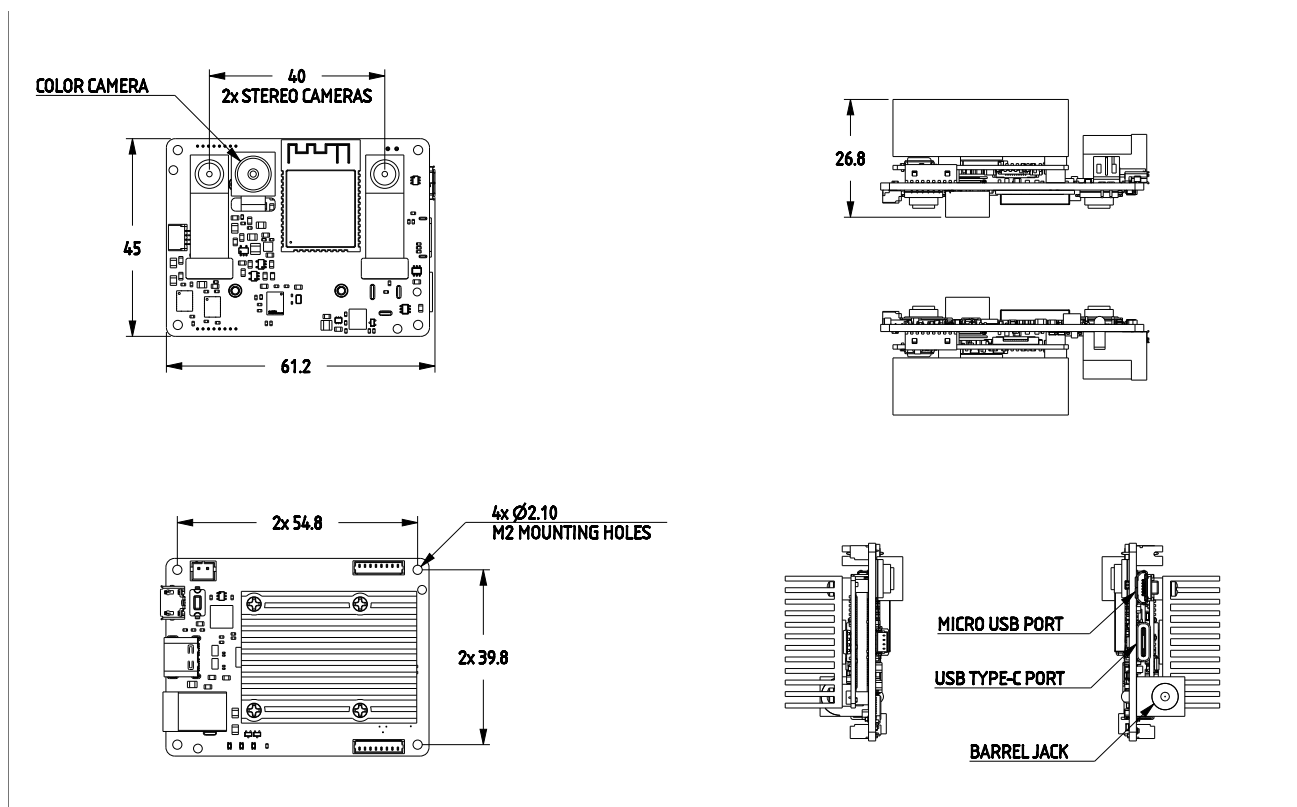
This OAK device is built on top of the RVC2. Main features:

- **4 TOPS** of processing power (1.4 TOPS for AI - RVC2 NN Performance)
- **Run any AI model**, even custom-architected/built ones - models need to be converted.
- **Encoding:** H.264, H.265, MJPEG
- **Computer vision:** warp/dewarp, resize, crop via ImageManip node, edge detection, feature tracking. You can also run custom CV functions
- **Stereo depth** perception with filtering, post-processing, RGB-depth alignment, and high configurability
- **Object tracking:** 2D and 3D tracking with ObjectTracker node

## Dimensions and Weight

- Width: 60 mm

- Height: 45 mm
- Length: 25 mm (including the SoM)
- Weight: 45.5g (total), 20g (PCBA), 25.5g (SoM with heatsink)



## Stereo depth perception

This OAK-D-IOT-40 camera has a baseline of 4.0cm - the distance between the left and the right stereo camera. Minimal and maximal depth perception (MinZ and Max) depends on camera FOV, resolution, and baseline- more information [here](#).

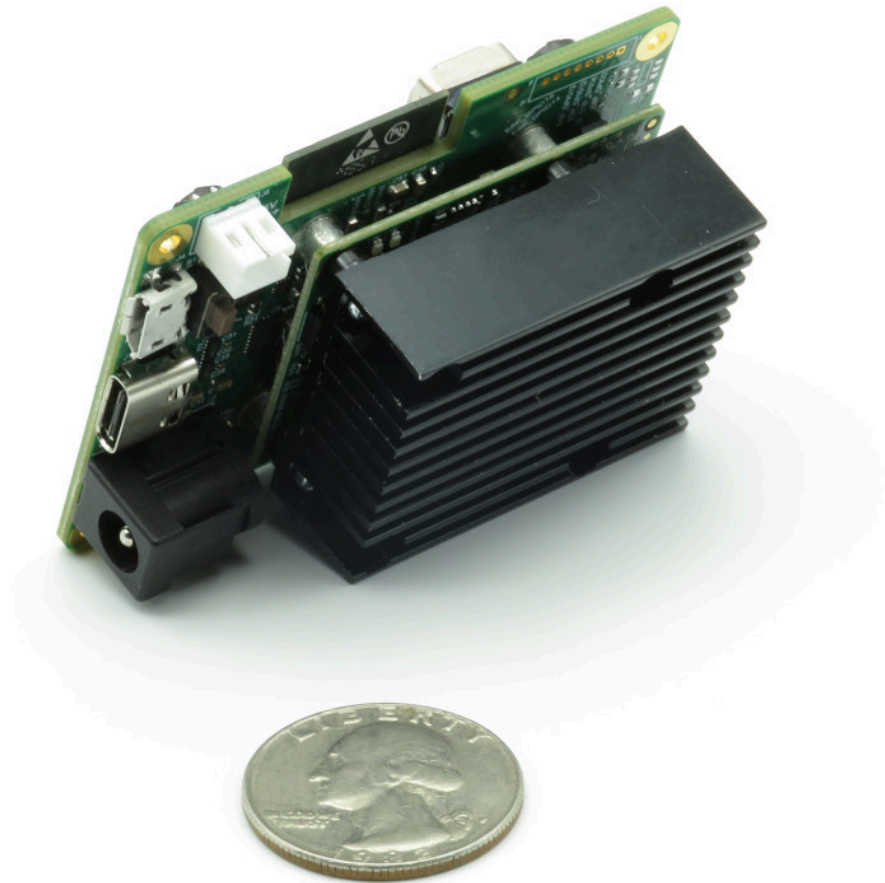
- Ideal range: 40cm - 4m
- MinZ: ~20cm (400P **OR** 800P, extended), ~37cm (800P)
- MaxZ: ~6 meters with a variance of 10%

Extended means that StereoDepth node has Extended disparity mode enabled.

## Getting started

The OAK-D-IoT-40 accepts power input from 5V barrel jack and it can also accept power from USB C connector. Booting can be accomplished from either the ESP32 or NOR flash on the BW1099EMB, boot selection is configured on BW1099EMB with BOOT resistors.

- The reset button resets the [OAK-SoM-IoT](#) only.
- The 5V LED indicates 5V power is present on the DM1092.
- The PG LED indicates “power good” from the OAK-SoM-IoT.
- The “RUN” LED indicates that the OAK-SoM-IoT is not reset.



## Power consumption

Most of the power is consumed by the RVC2, so the power consumption mostly depends on the workload of the VPU:

- Base consumption + camera streaming: 2.5W - 3W
- AI subsystem consumption: Up to 1W
- Stereo depth pipeline subsystem: Up to 0.5W
- Video Encoder subsystem: Up to 0.5W

So the total power consumption can be up to ~5W if you are using all the features at 100% at the same time. To reduce the power consumption, you can reduce FPS of the whole pipeline - that way, subsystems won't be utilized at 100% and will consume less power.

## Operating temperature

The ambient operating temperature of RVC2 based devices is between -20°C and 50°C when fully utilizing the VPU.

Similarly to the [Power consumption](#), max operating temperature depends on VPU utilization. The higher the VPU utilization, the more heat the VPU will generate. The RVC2 VPU can continuously operate at 105 °C, after which the depthai library will automatically shut down the device (to avoid chip damage).

To find out more, see our [Operative temperature range](#) documentation.

## 3D Models

- Board STEP files [here](#)

## Files

- [Altium Design Files](#)
- [Assembly Drawing](#)
- [Assembly Outputs](#)
- [Fabrication Drawing](#)
- [Fabrication Outputs](#)
- [Schematic](#)

## Got questions?

Head over to [Discussion Forum](#) for technical support or any other questions you might have.